

# **PFM of Piezoelectric Materials: Contact Mechanics and Resolution Theory**

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# **Piezoresponse Force Microscopy**

## **5.1. Contact mechanics of PFM**

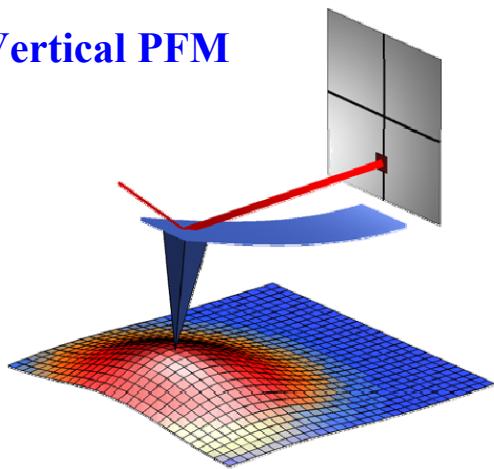
- 5.1.1. Exact solutions
- 5.1.2. Decoupled approximation
- 5.1.3. Implications for imaging

## **5.2. Resolution theory in PFM**

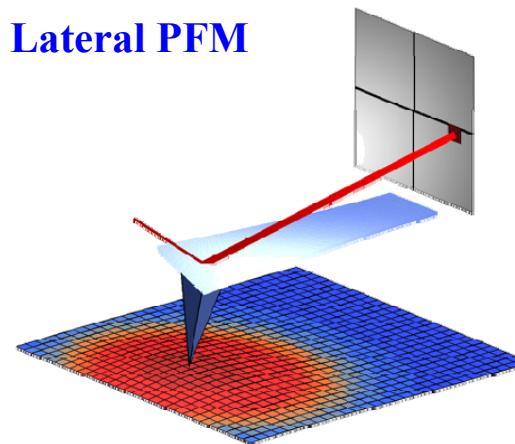
- 5.2.1. Resolution and Information limit
- 5.2.2. Tip calibration
- 5.2.3. Image reconstruction

# *Probing NanoElectromechanics*

Vertical PFM



Lateral PFM



## *Piezoresponse Force Microscopy*

Application of AC bias to the tip

$$V_{tip} = V_{dc} + V_{ac} \cos(\omega t)$$

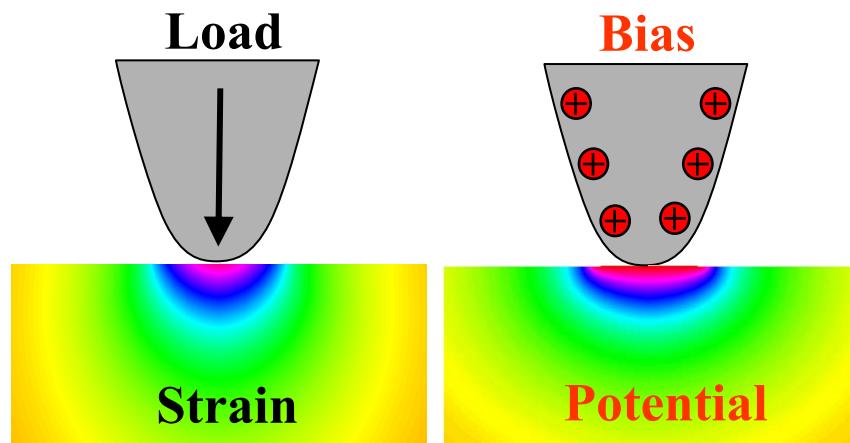
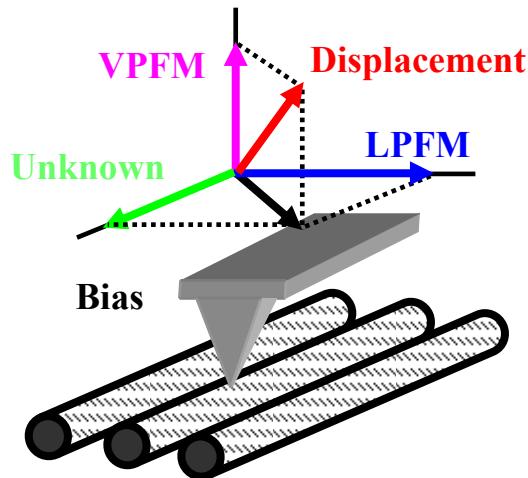
results in cantilever deflection

$$d = d_0 + A(\omega, V_{dc}) V_{ac} \cos(\omega t + \varphi)$$

due to piezoelectric effect

**PFM = Nanoelectromechanics**

# *Image formation in PFM*



In piezoelectric materials, electrical and mechanical phenomena are coupled

Several competing contributions:

1. Vertical surface response
2. Longitudinal response
3. Torsional response
4. Local electrostatic force
5. Distributed electrostatic force

1. Tip-surface contact mechanics
  - origins of PFM signal
2. Cantilever dynamics
  - Detection mechanism
3. Field structure in material
  - Resolution
  - hysteresis measurements
  - switching phenomena

# Electromechanical Coupling in SPM

## Contact Electromechanical Techniques

Piezoresponse Force Microscopy

$$\left( \frac{\partial z}{\partial V} \right)_F$$

Ultrasonic-Electrostatic Microscopy

$$\frac{\partial^2 F}{\partial z \partial V}$$

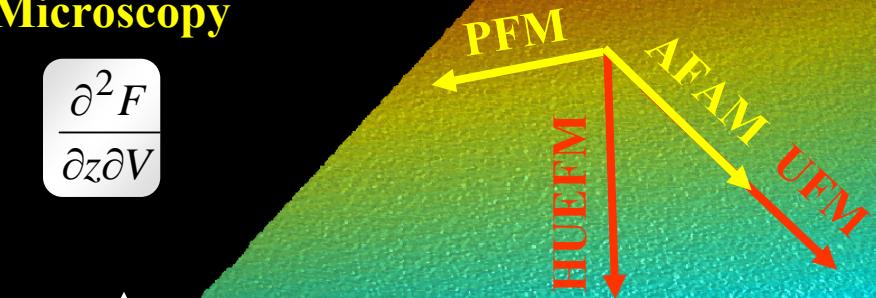
$$F = F(z, V_{\text{tip}})$$

Atomic Force Acoustic Microscopy

$$\frac{\partial F}{\partial z}$$

Ultrasonic Force Microscopy

$$\frac{\partial^2 F}{\partial z^2}$$



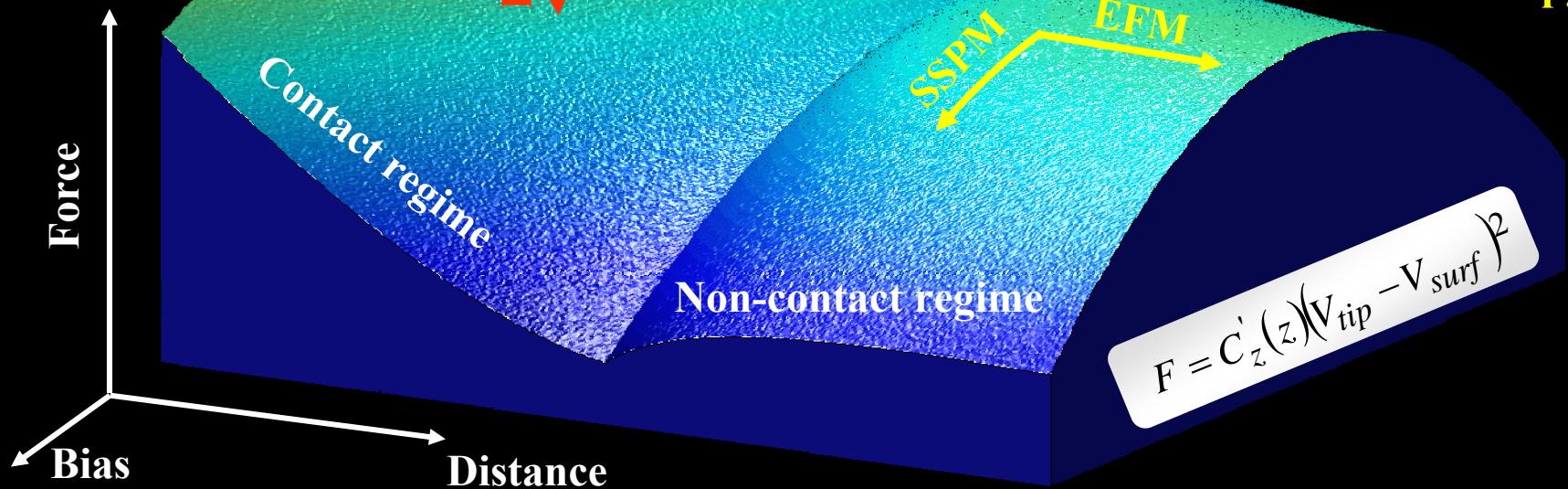
## Non-contact Techniques

Electrostatic Force Microscopy

$$\frac{\partial F}{\partial z}$$

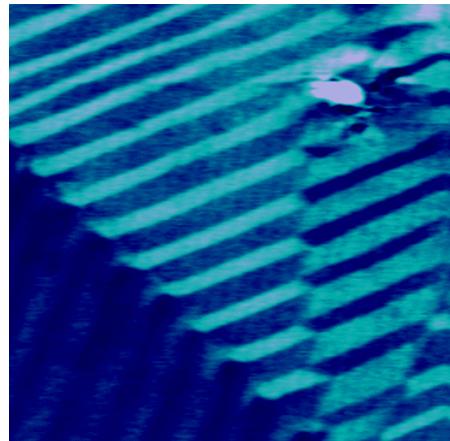
Scanning Surface Potential Microscopy

$$\frac{\partial F}{\partial V}$$

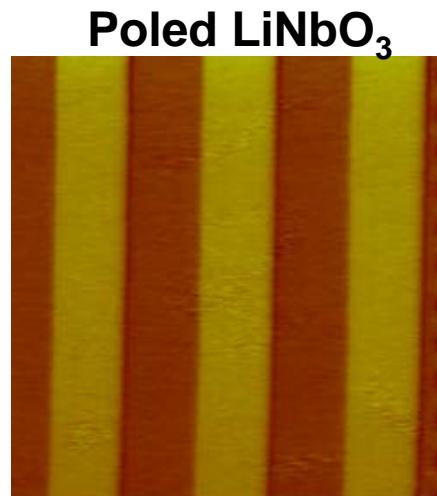


# Piezoresponse Force Microscopy of Materials with Out-of-Plane Polarization

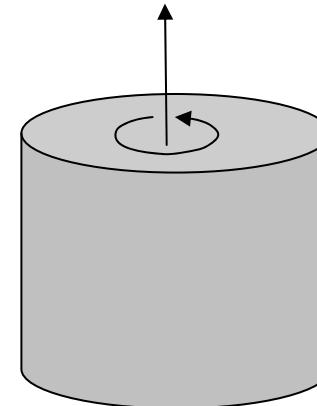
Examples:  $c^+$ - $c^-$  domains in  $\text{BaTiO}_3$ , periodically poled  $\text{LiNbO}_3$ , poled polymers



$\text{BaTiO}_3$



Poled  $\text{LiNbO}_3$

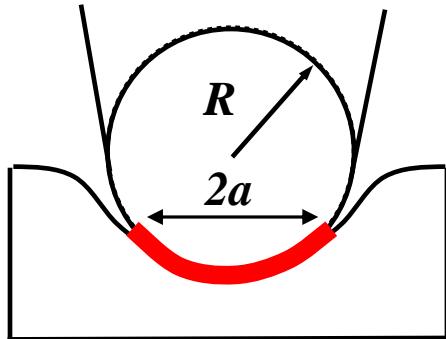


For piezoelectric and elastic properties, tetragonal and hexagonal symmetries are equivalent to transversally isotropic

- The highest symmetry possible for ferroelectric material
- No lateral response component
- A rigorous electromechanical solution exists!
- Starting point to more complex systems

# Nanoelectromechanics of PFM

## Stiffness Relations



**1872:** Hertz – spherical indentation of isotropic material

**1945:** Sneddon – arbitrary indentor shape

**1992:** Hanson: transversally isotropic material

**2002:** Karapetian and Kachanov: piezoelectric material

Indentation depth:  $w_0 = \frac{a^2}{R}$

Load:  $P = \frac{4a^3 C_1^*}{3\pi R} + \frac{2a\psi_0 C_3^*}{\pi}$

Charge:  $Q = -\frac{4a^3 C_3^*}{3\pi R} + \frac{2a\psi_0 C_4^*}{\pi}$

$a$  – indentation radius,  $R$  – tip radius

$C_1^*$

**Indentation elastic stiffness**

$C_3^*$

**Indentation piezoelectric coefficient**

$C_4^*$

**Indentation dielectric constant**

This is the first **rigorous solution** of spherical indentation problem for piezoelectric material **in analytical functions**.

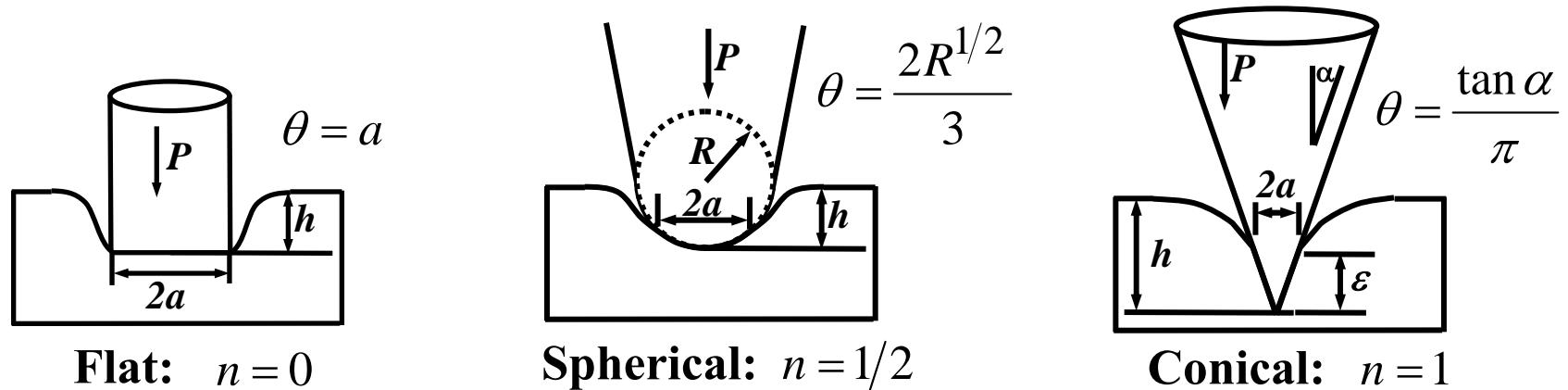
S.V. Kalinin, E. Karapetian, and M. Kachanov, Phys. Rev. **B**, 2004

E. Karapetian, M. Kachanov, and S.V. Kalinin, Phil. Mag. 2005

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# Nanoelectromechanics for Arbitrary Indentor



Flat:  $n = 0$

Spherical:  $n = 1/2$

Conical:  $n = 1$

<b>Load:</b>	$P = \frac{2}{\pi} \theta \left( h^{n+1} C_1^* + (n+1) h^n \psi_0 C_3^* \right)$
<b>Charge:</b>	$Q = \frac{2}{\pi} \theta \left( -h^{n+1} C_3^* + (n+1) h^n \psi_0 C_4^* \right)$

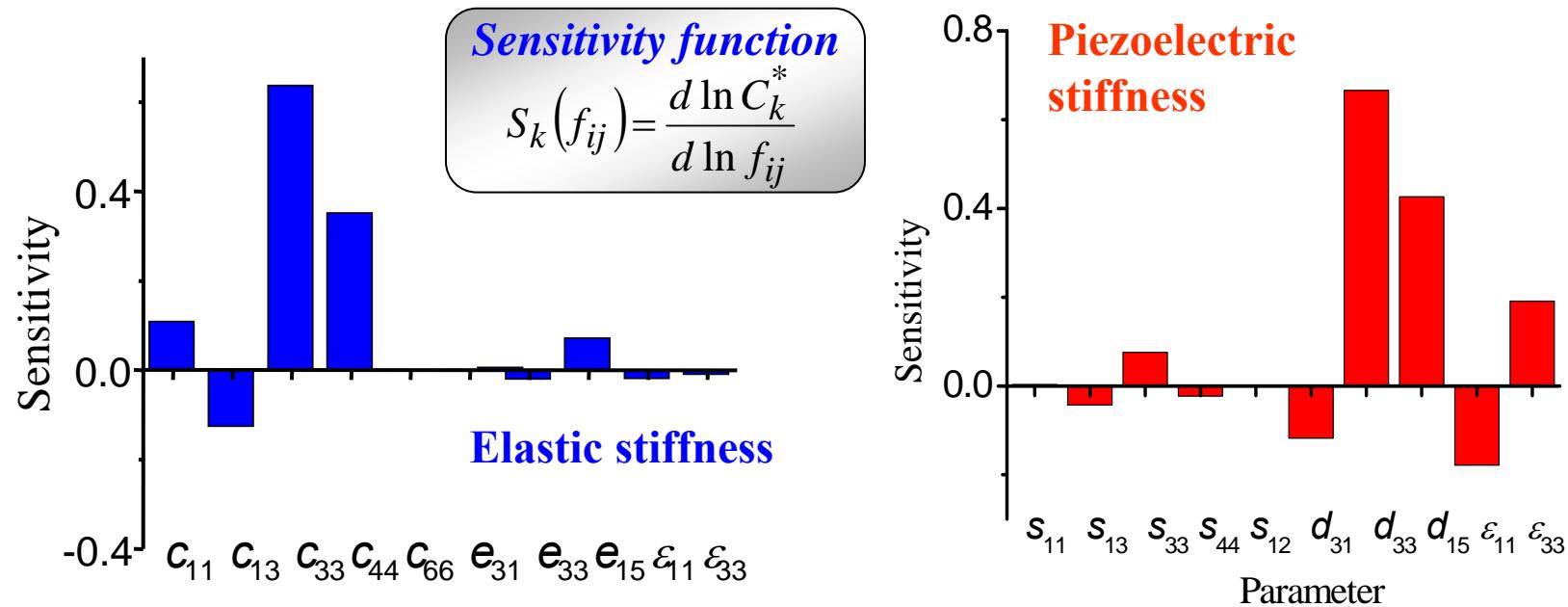
*For uniform field:*

$h = d_{33} V$
$Q = d_{33} F$

## Implications:

1. In the SPM or indentation experiment, we can determine only indentation moduli, but not the individual elements of elastic, piezoelectric or dielectric tensors
2. In contact problem, indenter shape function and materials properties are decoupled, hence the indenter can be calibrated
3. Experimentally, we can measure  $C_3/C_1$  by PFM and  $C_1$  by e.g. Atomic Force Acoustic Microscopy. In SPM, due to smallness of capacitance,  $C_4$  can not be measured directly

# Materials Properties and Effective Response

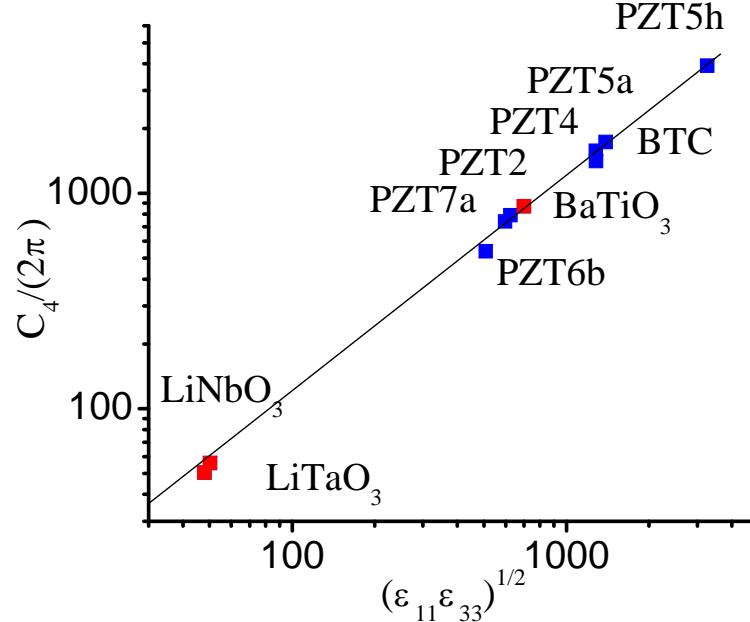
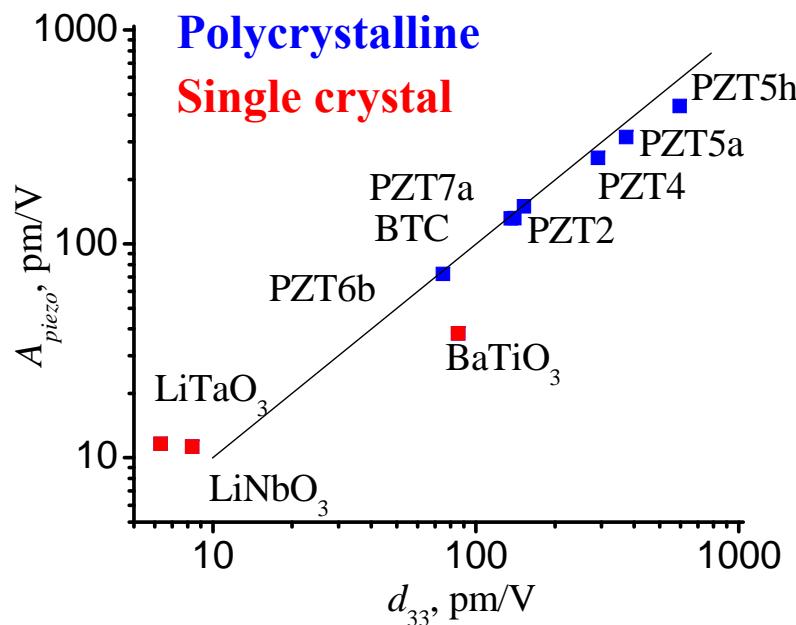


Indentation stiffnesses are complex functions of materials properties:

$$C_i^* = C_i^*(c_{ij}, d_{ij}, \epsilon_{ij})$$

- Elastic indentation module is determined primarily by  $c_{ij}$
- PFM signal is determined by  $d_{ij}$  and  $\epsilon_{ij}$
- Dielectric properties are determined by  $\epsilon_{ij}$

# Materials Properties and Effective Response



- Piezoresponse amplitude is a complex function of materials constants
- There is a reasonable correlation between PFM signal and  $d_{33}$
- Indentor charge can be obtained from simple theory

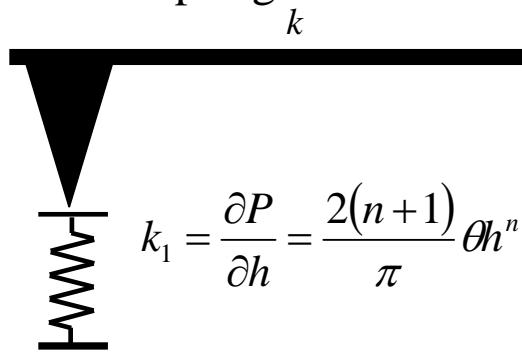
# Implications for Electromechanical and Mechanical SPM

$$P = \frac{2}{\pi} \theta \left( h^{n+1} C_1^* + (n+1) h^n V_{tip} C_3^* \right)$$

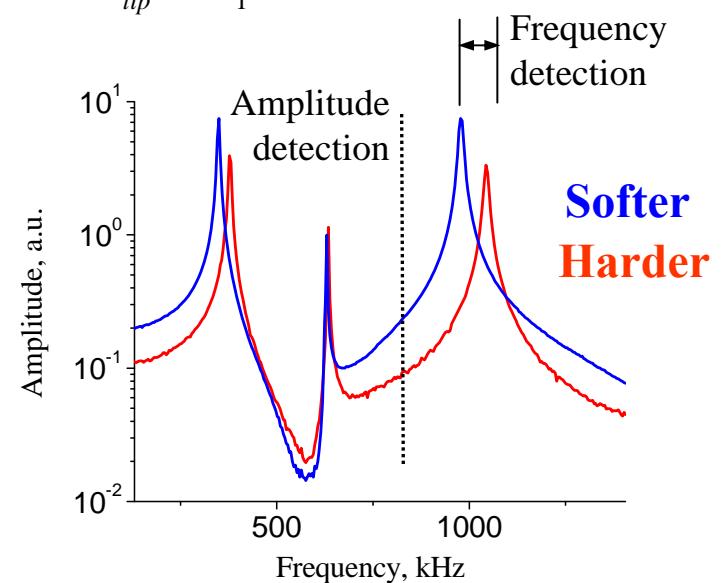
In Piezoresponse Force Microscopy, measured is  
Independent of tip geometry

$$d_{eff} = \frac{\partial h}{\partial V_{tip}} = \frac{C_3^*}{C_1^*}$$

In Atomic Force Acoustic Microscopy, signal is related  
to tip-surface spring constant.



$$k_1 = \frac{\partial P}{\partial h} = \frac{2(n+1)}{\pi} \theta h^n C_1^*$$



**Positive:** PFM signal is independent on tip geometry and topography

**Negative:** we can not use resonant enhancement in PFM

# **Approximate Theory for PFM**

**Rigorous solution is limited:**

- Ignores fields outside the contact area (classical limit)
- Limited to transversally-isotropic material
  - no lateral PFM
  - no materials other than (100) surfaces of hexagonal perovskites
- Can not be used to describe PFM signal in
  - thin films
  - nanoparticles
  - domain wall profiles
  - cylindrical domains (PFM spectroscopy)

**We need approximate solutions!**

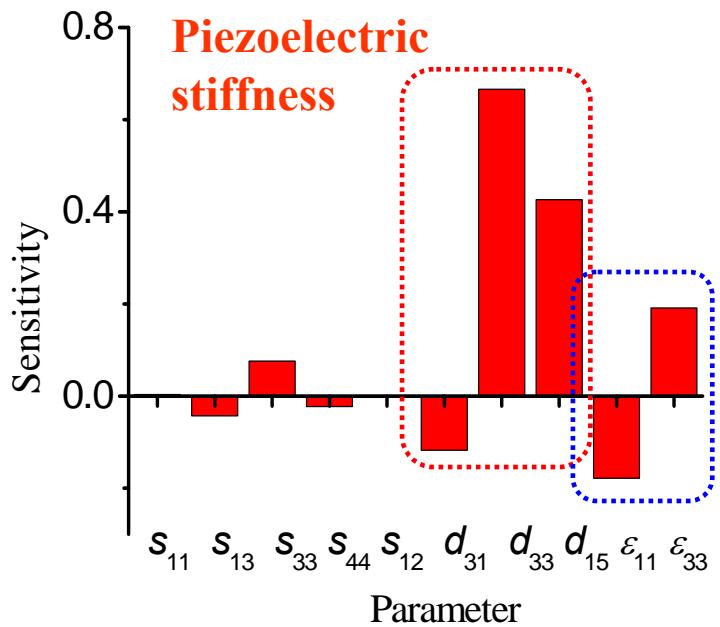
# **Green's Function Model**

**From rigorous solution, we know that far from contact, fields rapidly approach that for point charge/point force**

**Rigorous solution:** For fully anisotropic materials, the Green's function for point charge/point force for coupled electromechanical problem has recently been derived using linear plane wave method. (V. Borovikov, 2005)

- Arbitrary materials symmetry
  - Can describe vertical and lateral PFM
- Unphysical singularity at origin
  - can not describe switching and spectroscopy
- Ignores effects of tip shape, contact vs. non-contact contributions, etc.

# Decoupled Green's Function Model



The sensitivity analysis of exact solution suggests that approximate solution can be found as

$$u_3(\mathbf{x}) = d_{33}f_1(\varepsilon_{11}/\varepsilon_{33}) + d_{15}f_2(\varepsilon_{11}/\varepsilon_{33}) + d_{31}f_3(\varepsilon_{11}/\varepsilon_{33})$$

For general anisotropy

$$u_i(\mathbf{x}) = \sum_{jk} d_{ijk} f_{jk}(\varepsilon_{11}/\varepsilon_{33})$$

## Decoupled approximation

- Calculate electric field for rigid dielectric,  $d_{ijk} = 0$
- Calculate stress field using piezoelectric constitutive equations,  $X_{ij} = E_k d_{kij}$
- Calculate displacement field using Green's function for non-piezoelectric elastic solid

$$u_i(\mathbf{x}) = \int_0^\infty d\xi_3 \int_{-\infty}^\infty d\xi_2 \int_{-\infty}^\infty d\xi_1 \frac{\partial G_{ij}(\mathbf{x}, \boldsymbol{\xi})}{\partial \xi_k} E_l(\boldsymbol{\xi}) c_{kjmn} d_{lnm}$$

# **Decoupled Green's Function Model**

**Benefits of decoupled approximation:**

- Can take into account any field structure (solve electrostatic problem)
- Arbitrary materials symmetry (as given by dielectric, piezoelectric, and elastic tensors)
- Can naturally be used to describe microstructural elements such as variations in elastic properties, domain walls, etc.
- Can be further simplified by assuming special materials symmetries for elastic and mechanical properties

**Error estimate:** From  $D_i = d_{ijk} X_{jk} + \varepsilon_{im} E_m$  we get  $E_k = \varepsilon_{ki}^{-1} D_i - \varepsilon_{ki}^{-1} d_{ijl} X_{jl}$

Substituting into  $U_{ij} = s_{ijkl} X_{kl} + E_m d_{mij}$

we obtain  $U_{ij} = \left(1 - s_{ijkl}^{-1} \varepsilon_{mp}^{-1} d_{plk} d_{mij}\right) s_{ijkl} X_{kl} + \varepsilon_{mp}^{-1} d_{mij} D_p$

**BaTiO<sub>3</sub>:**  $k_{15}^2 \approx 0.32$     $k_{31}^2 \approx 0.10$     $k_{33}^2 \approx 0.31$

$$k_{ij}^2 = (d_{ij})^2 / (s_{jj} \varepsilon_{ii})$$

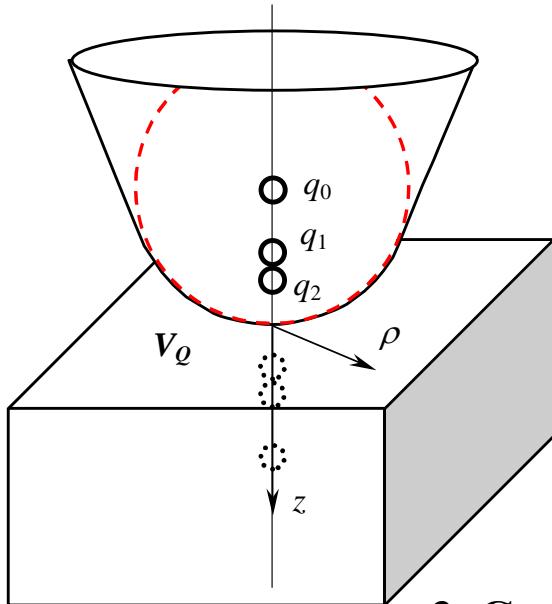
**PZT:**  $k_{15}^2 \approx 0.14$     $k_{31}^2 \approx 0.02$     $k_{33}^2 \approx 0.13$

**Quartz:**  $k_{11}^2 \approx 0.01$

**For most materials, error is of order of 10-30% or less!**

# Electric Field Structure

1. Represent tip using image charge series or multipole expansion



2. Solve Laplace's equation

$$\begin{cases} \epsilon_0 \epsilon_{ij} \frac{\partial^2}{\partial x_i \partial x_j} V(\mathbf{r}) = 0, & z \geq 0 \\ \epsilon_0 \Delta V_0(\mathbf{r}) = -Q \cdot \delta(z+d) \delta(x) \delta(y), & z < 0 \end{cases}$$

with boundary conditions

$$\begin{aligned} \epsilon_{3j} \frac{\partial}{\partial x_j} V(z=0) &= \frac{\partial}{\partial z} V_0(z=0), \\ V(z=0) &= V_0(z=0) \end{aligned}$$

3. General answer

$$V(\mathbf{r}) = \frac{Q}{2\pi\epsilon_0} \int_{-\infty}^{\infty} dk_x \int_{-\infty}^{\infty} dk_y \frac{\exp(-ik_x x - ik_y y)}{2\pi} \cdot \frac{\exp(-d\sqrt{k_x^2 + k_y^2} - z\lambda(k_x, k_y))}{\left(\sqrt{k_x^2 + k_y^2} + (i\epsilon_{31} k_x + i\epsilon_{32} k_y + \epsilon_{33}\lambda)\right)}$$

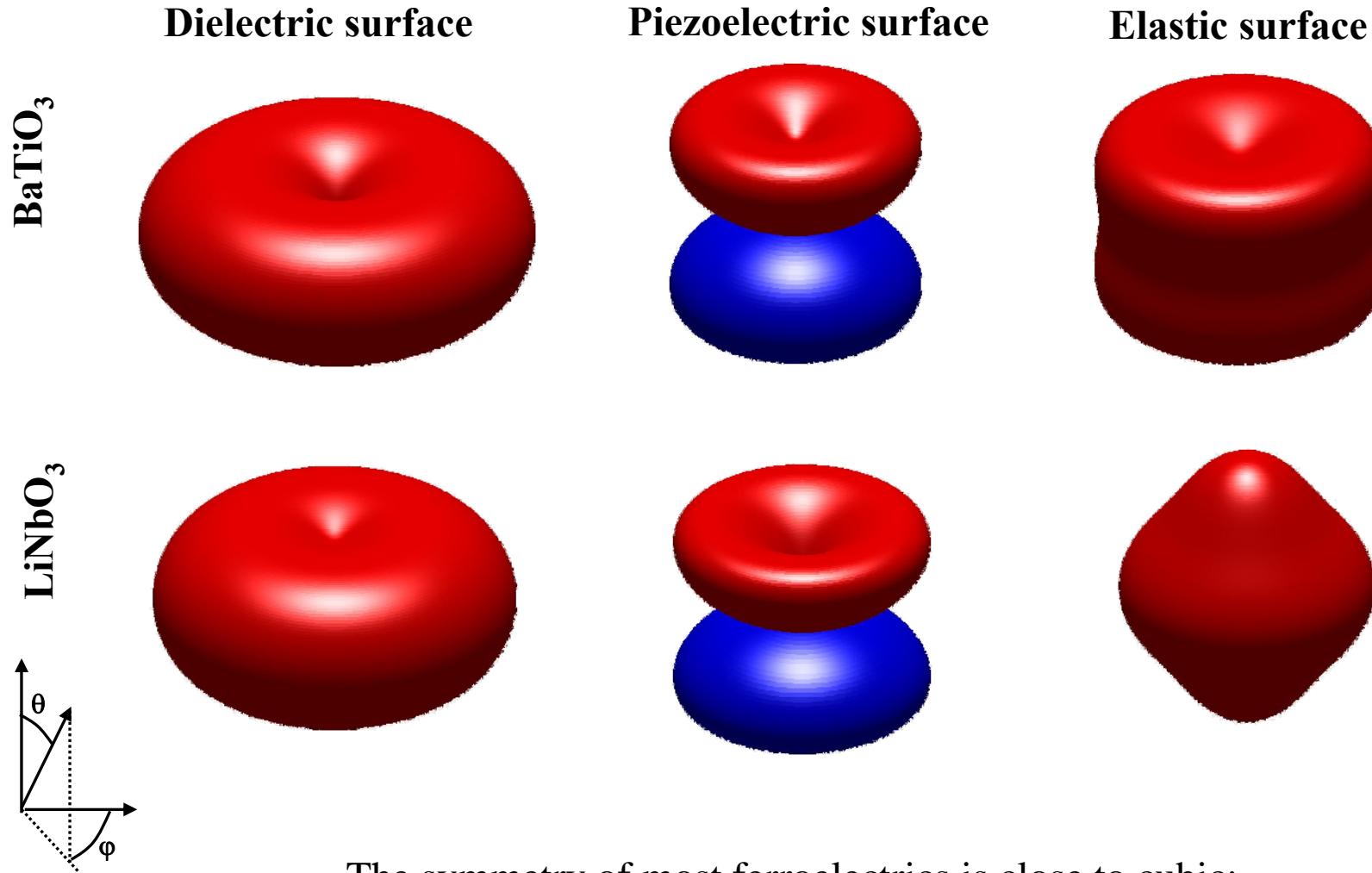
4. Transversally-isotropic

$$V_Q(\rho, z) = \frac{Q}{2\pi\epsilon_0(\kappa+1)} \frac{1}{\sqrt{\rho^2 + (z/\gamma + d)^2}}$$

**Dielectric constant**  $\kappa = \sqrt{\epsilon_{33}\epsilon_{11}}$

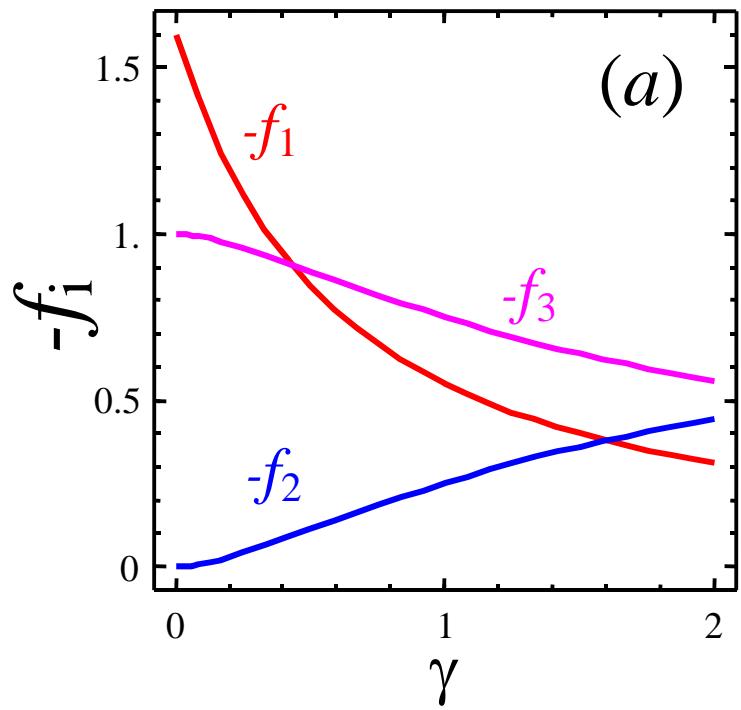
**Dielectric anisotropy**  $\gamma = \sqrt{\epsilon_{33}/\epsilon_{11}}$

# *Elastic Green's function*



The symmetry of most ferroelectrics is close to cubic:  
approximate elastic properties as isotropic!

# **Solution for Transversally Isotropic Material**



**Surface displacement:**

$$u_3(\rho) = \frac{Q}{2\pi\epsilon_0(1+\kappa)} \frac{d_{31}f_1(\gamma) + d_{15}f_2(\gamma) + d_{33}f_3(\gamma)}{\sqrt{\rho^2 + d^2}},$$

where

$$f_1(\gamma) = -\frac{1+2(1+\gamma)\nu}{(1+\gamma)^2}$$

$$f_2(\gamma) = -\frac{\gamma^2}{(1+\gamma)^2}$$

$$f_3(\gamma) = -\frac{1+2\gamma}{(1+\gamma)^2}$$

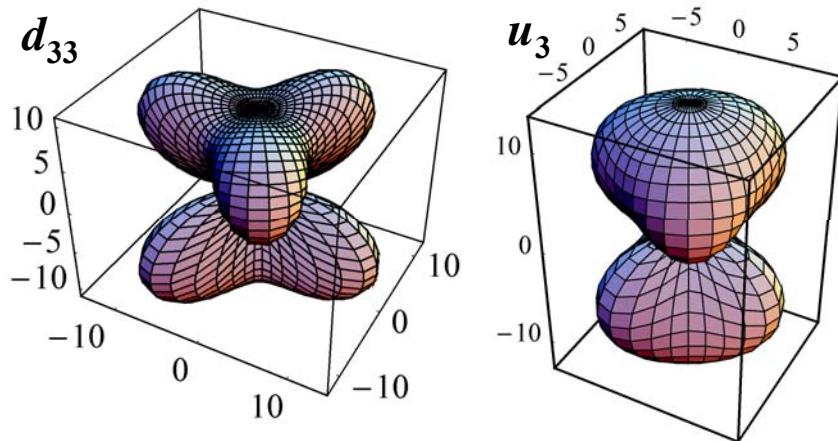
**Piezoresponse:**  $PR = d_{31}f_1(\gamma) + d_{15}f_2(\gamma) + d_{33}f_3(\gamma)$

**Response Theorem 1:** For a transversally isotropic piezoelectric solid in an isotropic elastic approximation and an arbitrary point charge distribution in the tip (not necessarily constrained to a single line), the vertical surface displacement is proportional to the surface potential induced by the tip in the point of contact

# Solution for General Anisotropy

For anisotropic material:  $u_i(\mathbf{x}) = V_Q(0)R_{ijkl}(\mathbf{x})d_{klj}$

where  $R_{imnl}(\mathbf{x}) = \frac{1}{V_Q(0)} \int_0^\infty d\xi_3 \int_{-\infty}^\infty d\xi_2 \int_{-\infty}^\infty d\xi_1 \frac{\partial G_{ij}(\mathbf{x}, \xi)}{\partial \xi_k} E_l(\xi) c_{kjmn}$



Piezoresponse surfaces for  $\text{LiNbO}_3$

For isotropic material:

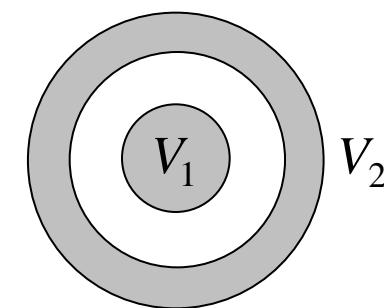
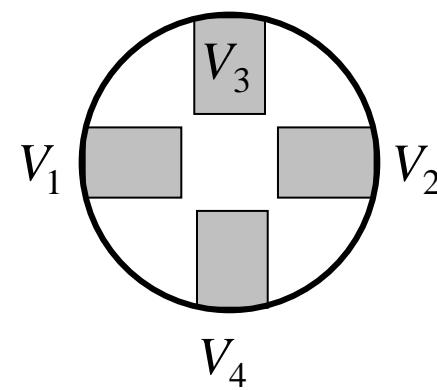
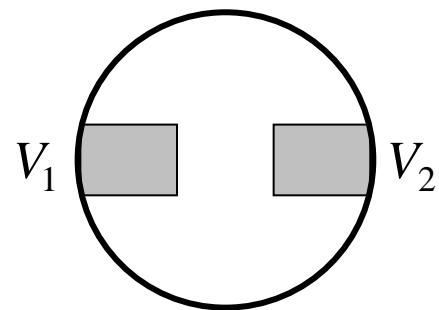
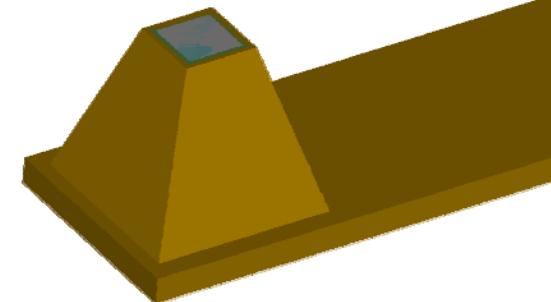
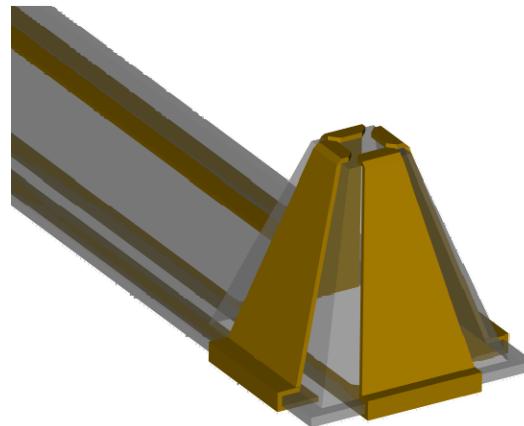
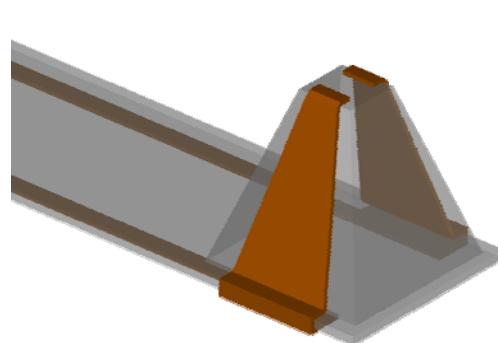
$$R_{121} = \frac{1 - 12v}{32}$$

$$R_{131} = -\frac{1}{8}$$

$$R_{111} = -\frac{13 + 4v}{32}$$

**Response Theorem 2:** For an anisotropic piezoelectric solid in the limit of dielectric and elastic isotropy, the vertical and lateral PFM signals are proportional to the potential on the surface induced by the tip if the tip charges and the point of contact are located on the same line along the surface normal.

# *Solutions for non-standard probes*



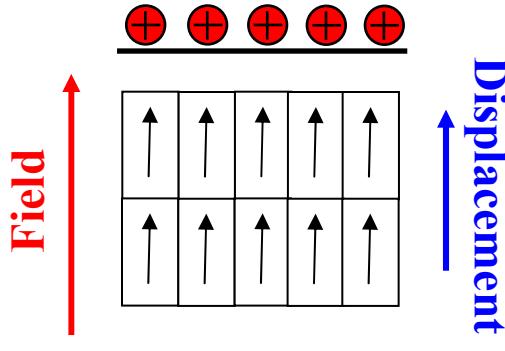
Strip-line

Quadrupole or rotating dipole

Shielded probe

# Principles of Orientation Imaging

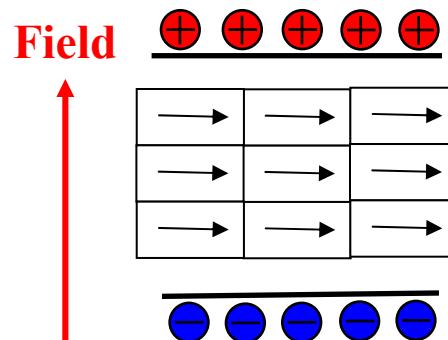
Experiment: measure the mechanical displacement in the applied electric field direction



If the field is  
**perpendicular** to the  
c-axis, the  
deformation in the  
field direction is zero

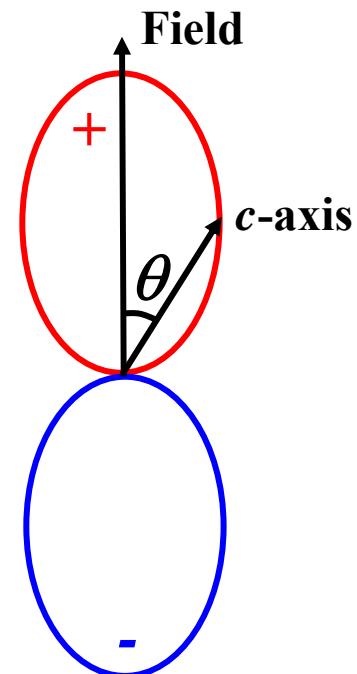
For tetragonal ferroelectric such as BaTiO<sub>3</sub>, if the field is **parallel** to the c-axis, there is strong deformation of the crystal in the field direction

$$\delta z = d_{33} E_3 h \quad \text{or} \quad \delta z = 80 \text{ V pm}$$



In the general case:

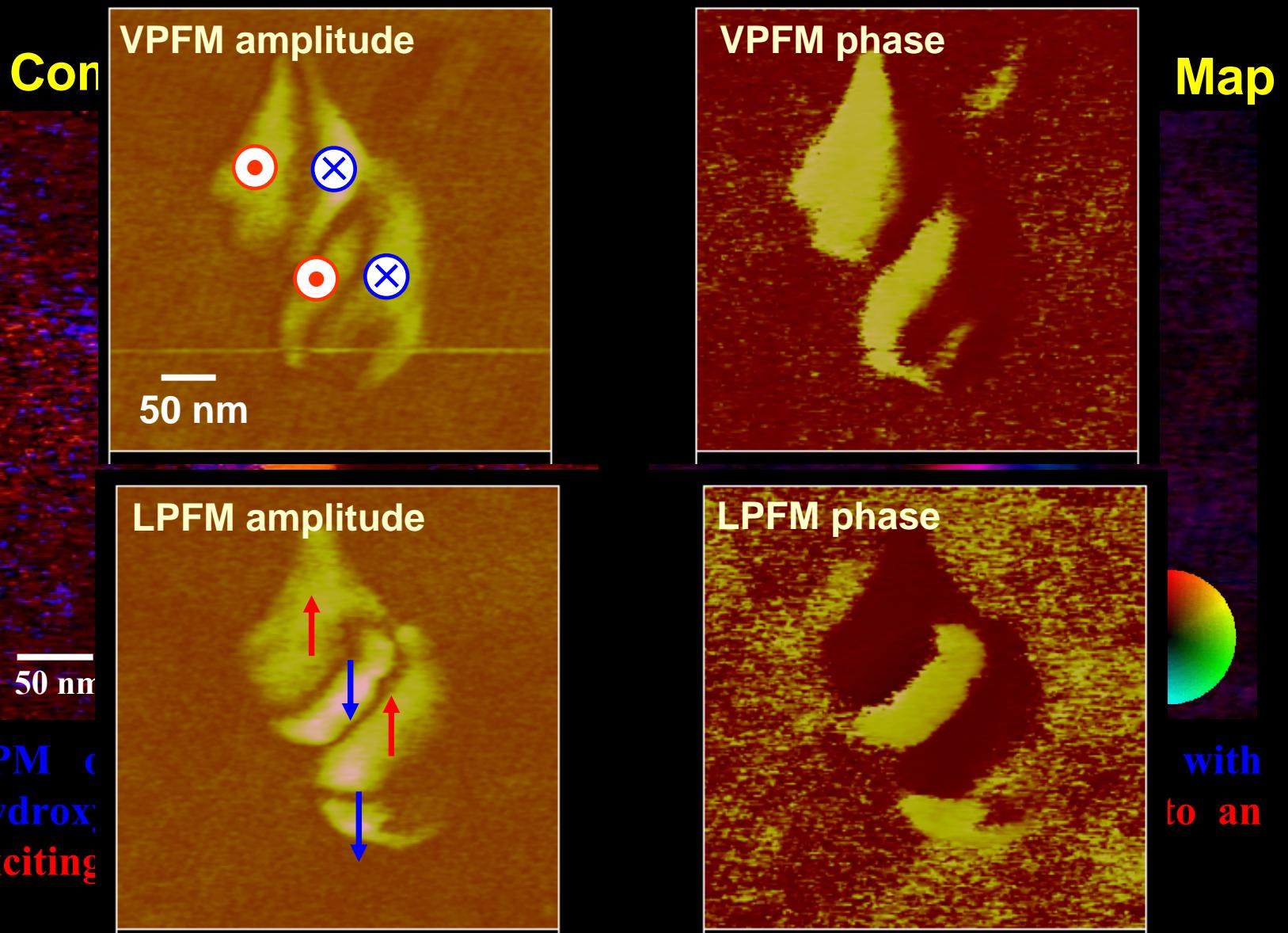
$$\delta z = (d_{15} + d_{31}) \sin^2 \theta \cos \theta + d_{33} \cos^3 \theta$$



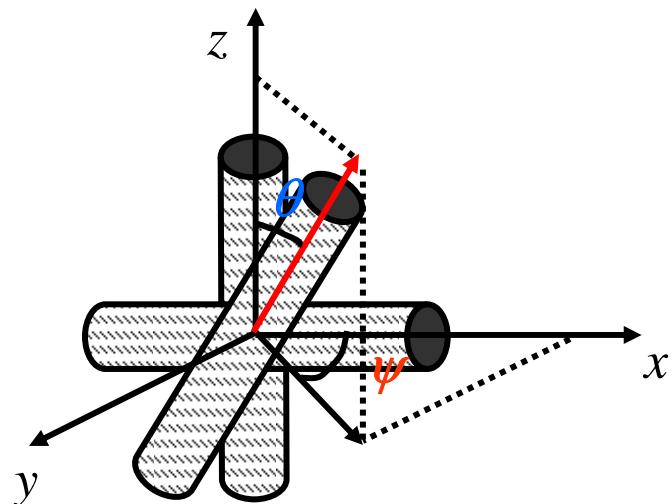
**From known electromechanical response, we can determine crystal orientation!**

- small displacements (10-100 pm)
- spatially localized (< 1 μm)

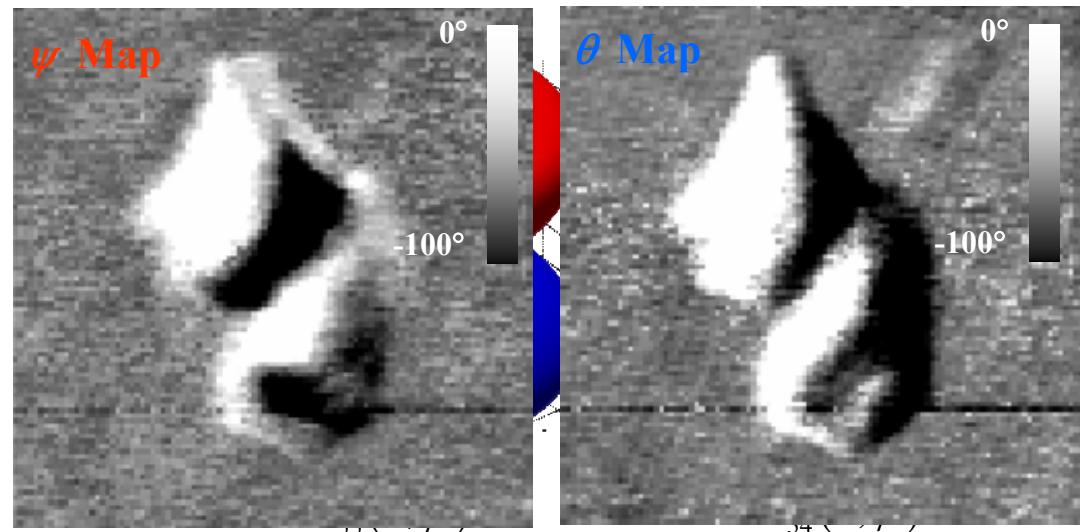
# Toward Single Molecule Imaging



# Molecular Orientation from PFM Data



Semiquantitative Orientation Response Surfaces for Collagen Fibril



Tetragonal material (4mm):

$$\begin{pmatrix} 0 & 0 & 0 & 0 & d\theta_5 & d\theta_5 \\ d\theta_1 & d\theta_3 & d\theta_1 & d\theta_5 & 0 & 0 \\ d\theta_1 & d\theta_1 & d\theta_3 & d\theta_5 & 0 & 0 \end{pmatrix}$$

Vertical PFM  
Lateral PFM (x)  
Lateral PFM (y)

$$d_{ij} = A_{ik}(\phi, \theta, \psi) \quad d_{kl}^o \quad N_{lj}(\phi, \theta, \psi)$$

$d_{ij}$  Piezotensor – lab coordinate system

$d_{kl}^o$  Piezotensor – crystal coordinate system

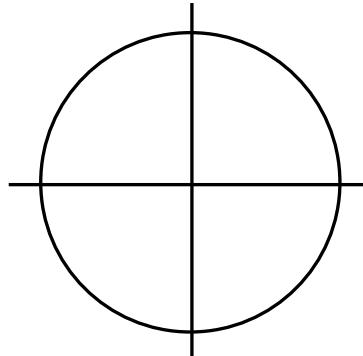
$N_{ij}(\phi, \theta, \psi)$   $A_{ij}(\phi, \theta, \psi)$  Rotation matrices

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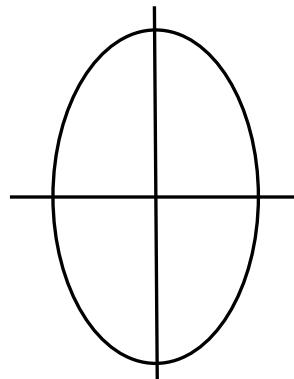
# *Can we do it any other way?*

*Scalar*



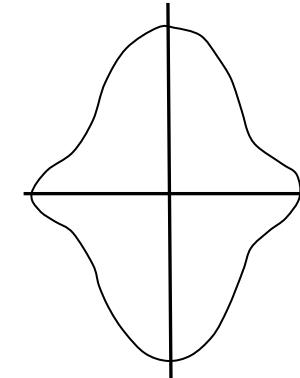
*Temperature,  
Potential, etc.*

*2<sup>nd</sup> order tensor*



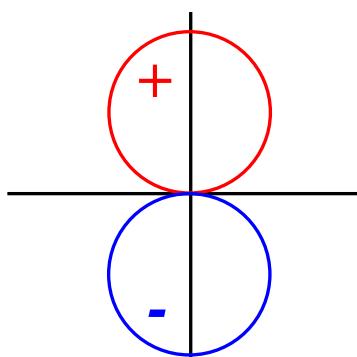
*Dielectric constant  
Thermal conductivity*

*4<sup>th</sup> order tensor*



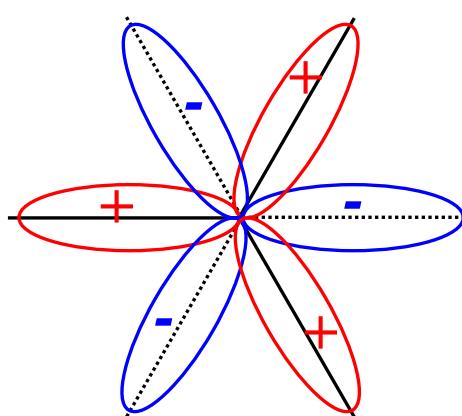
*Elasticity, Kerr effect  
Electrostriction*

*Vector*



*Polarization  
Magnetization  
Pyroelectricity*

*3<sup>d</sup> order tensor*



*Piezoelectricity  
Electrooptics, SHG*

**Orientation Imaging requires:**

1. Rank 3 tensor property
2. High spatial resolution
3. Insensitivity to tip geometry or easy calibration

**Piezoresponse Force  
Microscopy is perfect!**

**Ideally, we want to probe electromechanical behavior with  $\sim$ 1 pm/V sensitivity at  $\sim$ 0.1- 1 V excitation biases on molecular (biosystems) and unit cell (ferroelectrics) level.**

# ***Resolution Theory in PFM***

5.2.1. Linear imaging theory

5.2.2. Transfer function, resolution and information limit

5.2.3. Phenomenological resolution theory in PFM

- lock-in effect
- resolution function
- image reconstruction

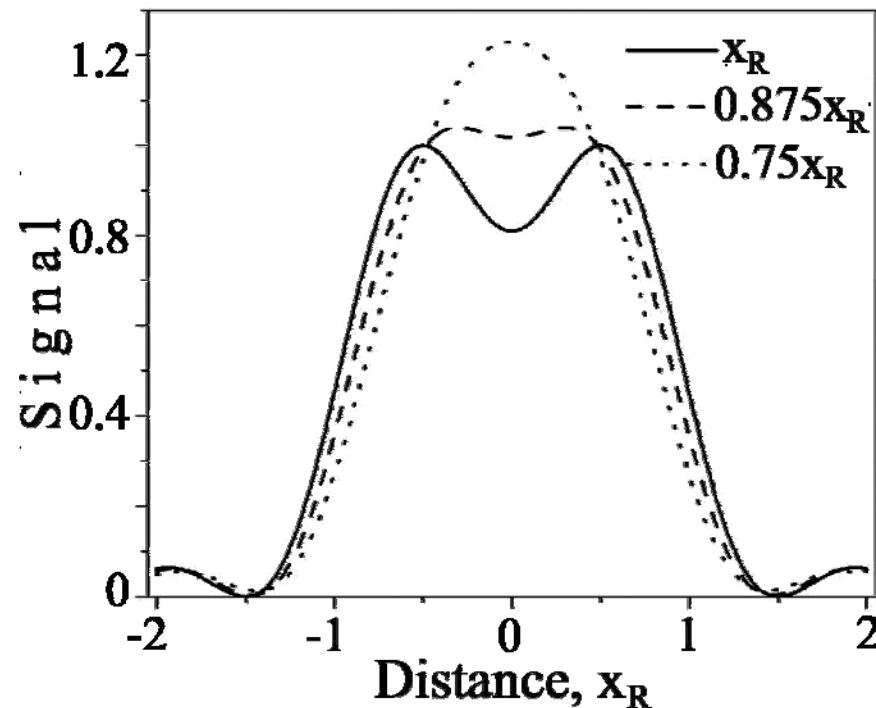
5.2.4. Analytical resolution theory in PFM

- Imaging domain walls and stripe domains
- Imaging cylindrical domains
- Effect of materials properties on resolution
- tip calibration

5.2.5. Implications for PFM data analysis

- statistical physics of domains
- domain wall width
- Writable domains
- Invisible domains

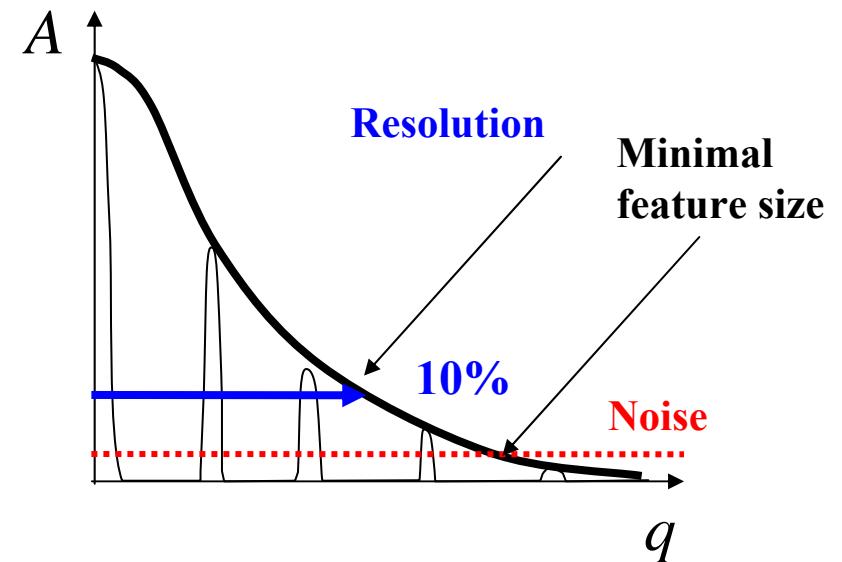
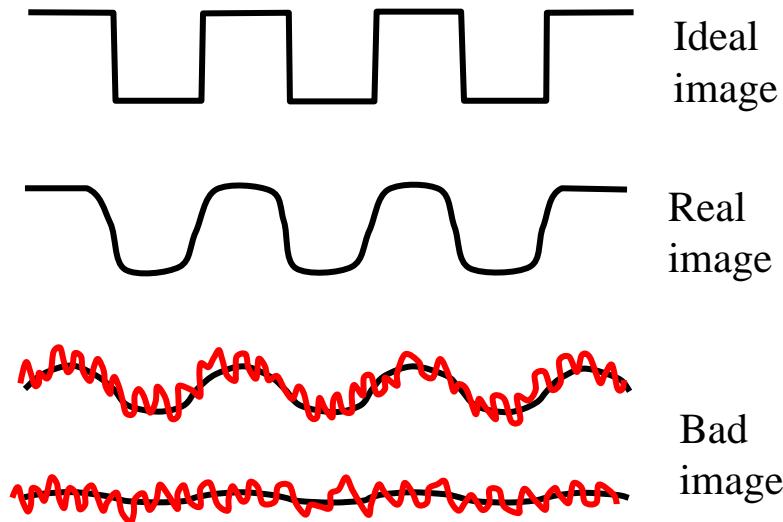
# *What is Resolution?*



Optics: Rayleigh criterion

# Transfer Function Theory

Real image always has contributions from probe and material



## Linear Imaging Theory

$$\text{Linear Imaging: } I(x) = \int I_0(x-y)F(y)dy + N(x)$$

$$\text{Ideal Image: } I_0(x-y) \quad \text{Transfer function: } F(y)$$

$$\text{Real Image: } I(x) \quad \text{Noise: } N(x)$$

$$\text{Fourier Transform: } I(q) = I_0(q)F(q) + N(q)$$

$$\text{Image Reconstruction: } I_0(q) = I(q)/F(q)$$

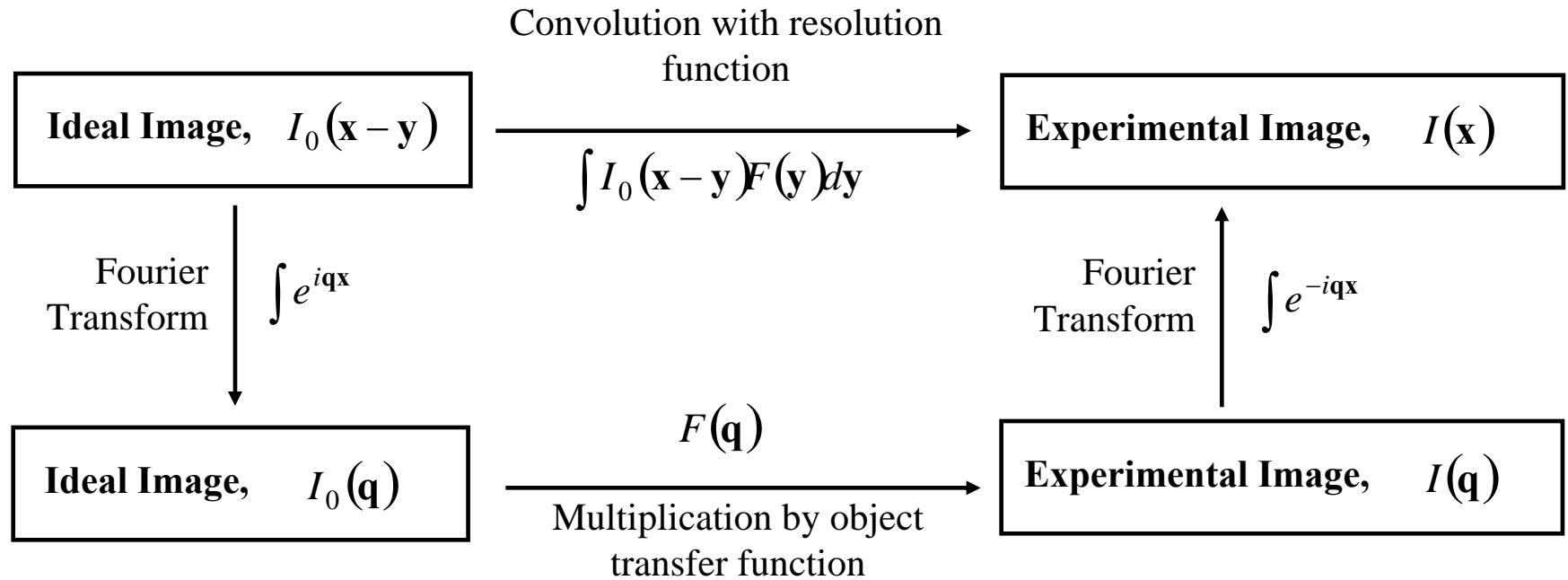
- Ideal image has all Fourier components
- Transfer function decays for high  $k$

We can define lateral resolution as:

- $q$  for which  $\text{TF} = 0.1 \text{ TF}(q=0)$
- smallest feature we can detect:

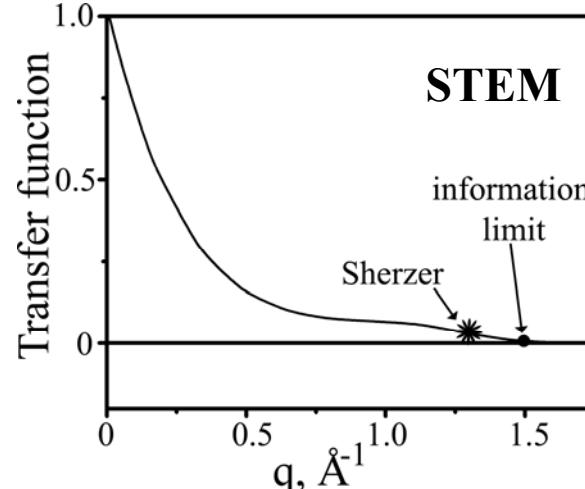
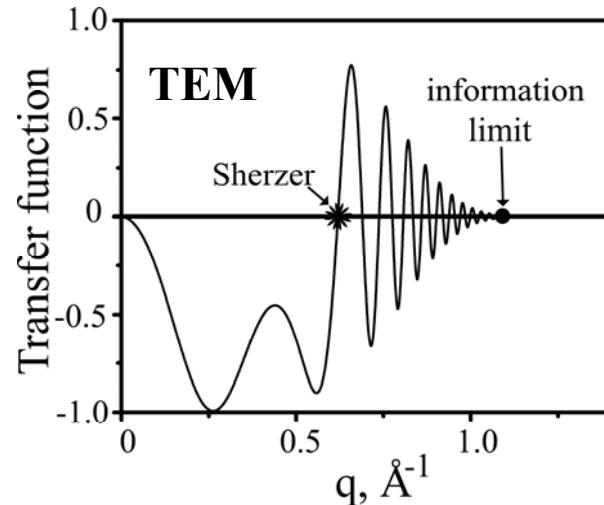
$$I_0(q)F(q) = N(q)$$

# **Transfer Function Theory**



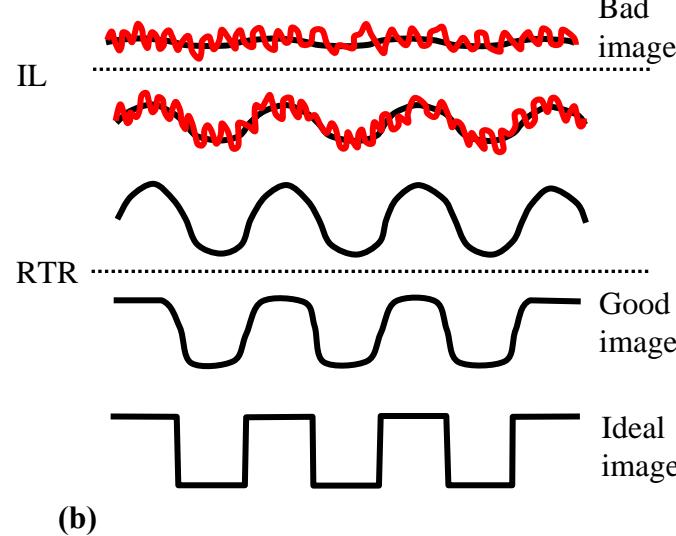
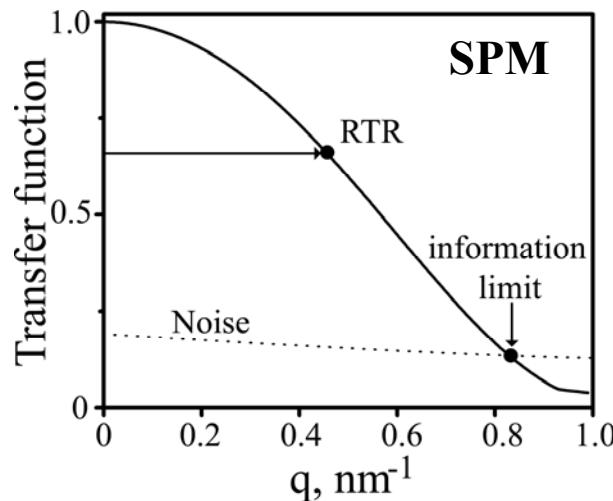
- Establish the resolution and information limits in PFM and its dependence on tip geometry and materials properties
- Develop the pathways for calibration of tip geometry
- Interpret the imaging and spectroscopy data in terms of intrinsic parameters
- Reconstruct the ideal image from experimental data,

# Resolution in Transfer Function Theory



In electron microscopy, zeroes in transfer function define Sherzer resolution

Information limit corresponds to frequencies above which there is no information transfer



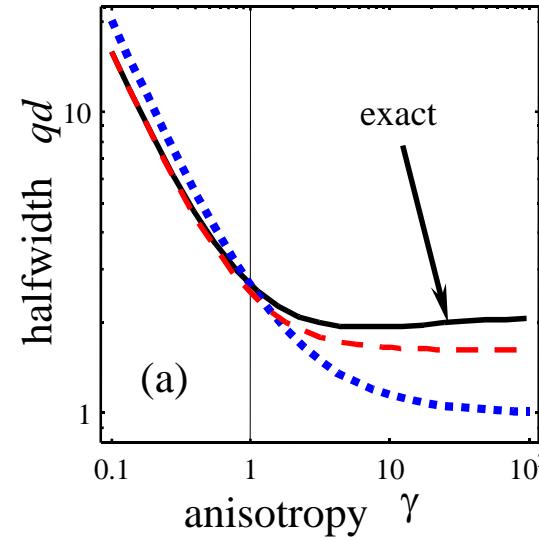
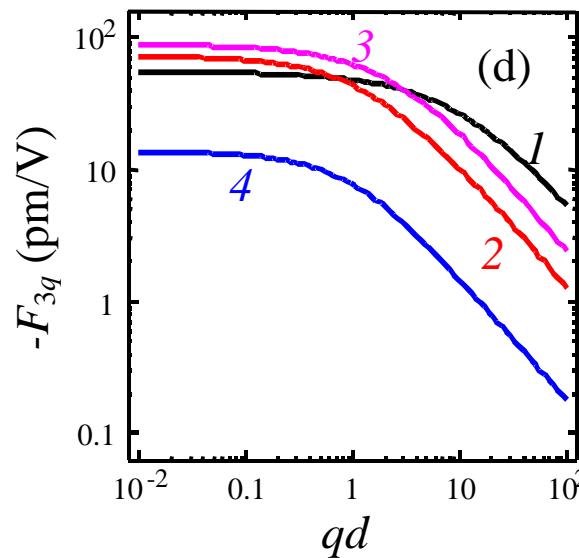
# Resolution in PFM

In decoupled approximation, PFM image formation mechanism is linear if material is uniform in z-direction,  $d_{mnk}(y - \mathbf{x}'', z) = d_{mnk}(y - \mathbf{x}'')$

**PFM Image:** 
$$u_3(\mathbf{0}, \mathbf{y}) = \int_{-\infty}^{\infty} d_{mnk}(\mathbf{y} - \boldsymbol{\xi}) F(\xi_1, \xi_2) d\xi_1 d\xi_2$$

**Transfer function:** 
$$F(\xi_1, \xi_2) = \int_{z=0}^{\infty} c_{jlmn} E_k(-\xi_1, -\xi_2, z) \frac{\partial}{\partial \xi_l} G_{3j}(\xi_1, \xi_2, z) dz$$

We calculate the resolution function in analytical form:



**Point charge model**

$$r_{\min} \approx \frac{\gamma \varepsilon_e R_0}{2\kappa} \frac{1+2\gamma}{(1+\gamma)^2}$$

**Sphere-plane model**

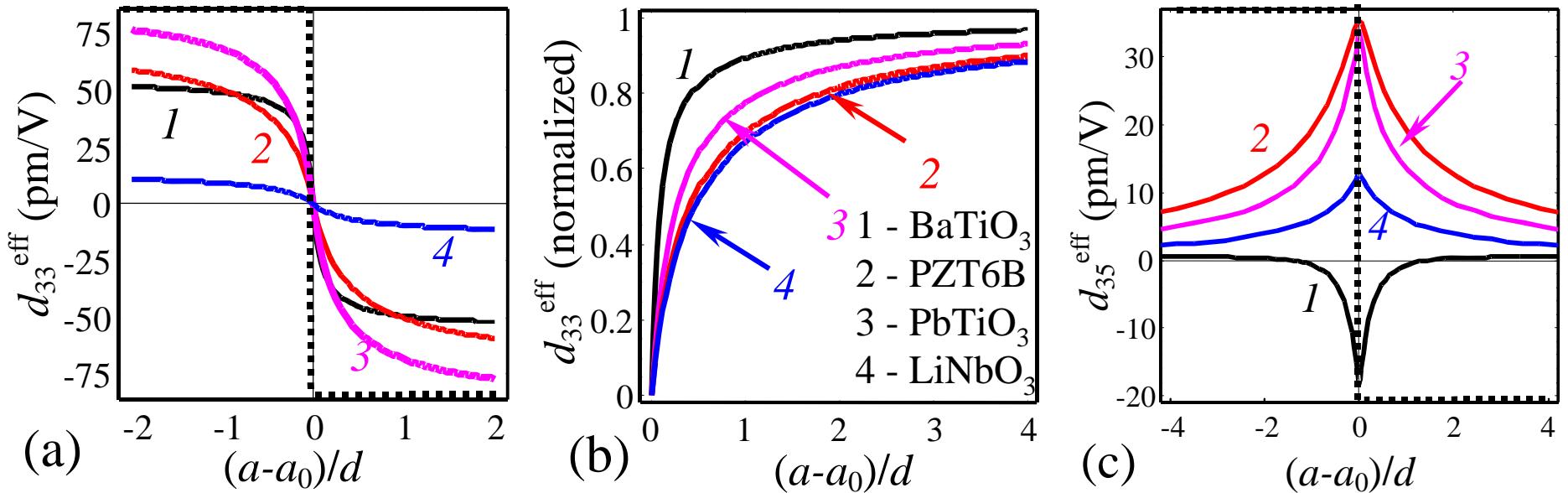
$$r_{\min} \approx \frac{\gamma \varepsilon_e R_0}{\varepsilon_e + \kappa} \frac{1+2\gamma}{(1+\gamma)^2}$$

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# Domain wall profile

Domain wall profile is a natural observable in PFM



**Vertical PFM**

$$d_{33}^{\text{eff}} \approx d_{03} + \left[ \frac{3}{4} \left( d_{33} + \left( \frac{1}{3} + \frac{4}{3} v \right) d_{31} \right) \frac{s}{|s| + 1/4} + \frac{1}{4} d_{15} \frac{s}{|s| + 3/4} \right]$$

**Lateral PFM**

$$d_{35}^{\text{eff}} \approx d_{01} + d_{33} \frac{3/8}{1 + 3|s|} + d_{31} \left( -\frac{3/8}{1 + 3|s|} + \frac{1+v}{1+4|s|} \right) + d_{15} \frac{2/\pi - 3/8}{1 + (8/\pi - 3/2)|s|}$$

We can use domain wall profile to calibrate the tip!

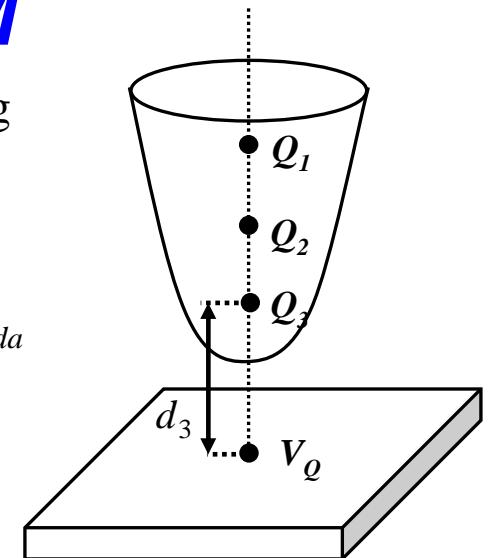
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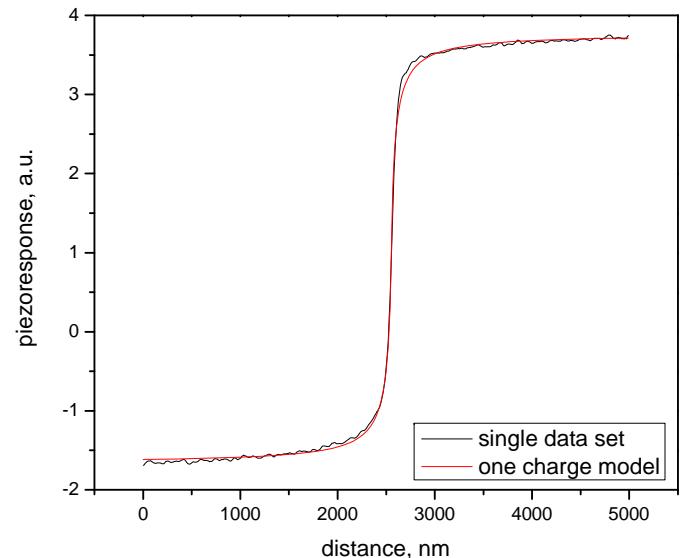
# Tip Calibration in PFM

We can determine tip parameters by fitting domain wall profile using model of superposition of point charges

$$F[u_3] = \int \left( PR(a) - \frac{1}{2\pi\epsilon_0(\epsilon_e + \kappa)} \sum_{m=0}^N \frac{Q_m}{d_m} \left( g_{313}\left(\frac{a-a_0}{d_m}, \gamma, \nu\right) d_{31} + g_{351}\left(\frac{a-a_0}{d_m}, \gamma\right) d_{15} + g_{333}\left(\frac{a-a_0}{d_m}, \gamma\right) d_{33} \right)^2 \right) da$$



Material	$\epsilon_e$	Width, nm	$Q$	$d$ , nm
LiNbO <sub>3</sub>	1	96	1000	92
Epitaxial PZT	1	107	2550	125
PZT in air	1	58	723	86.5
PZT in liquid	80	6	104	11.8

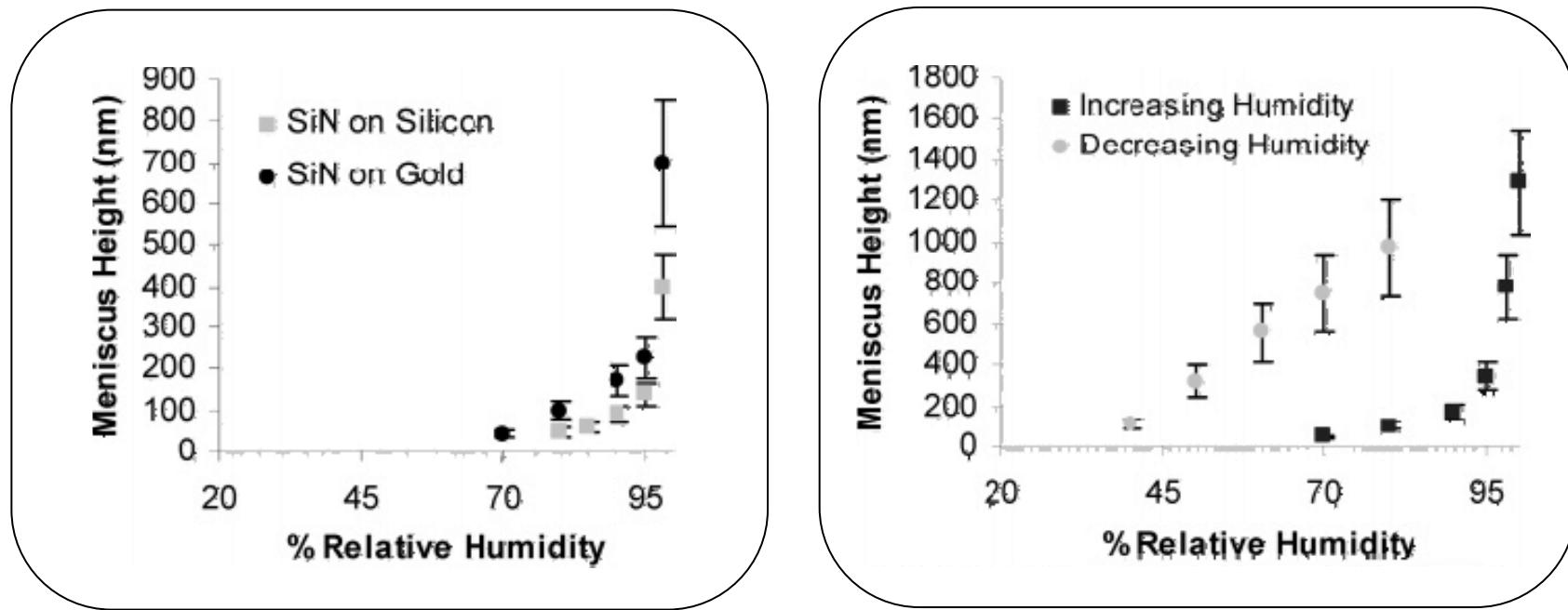
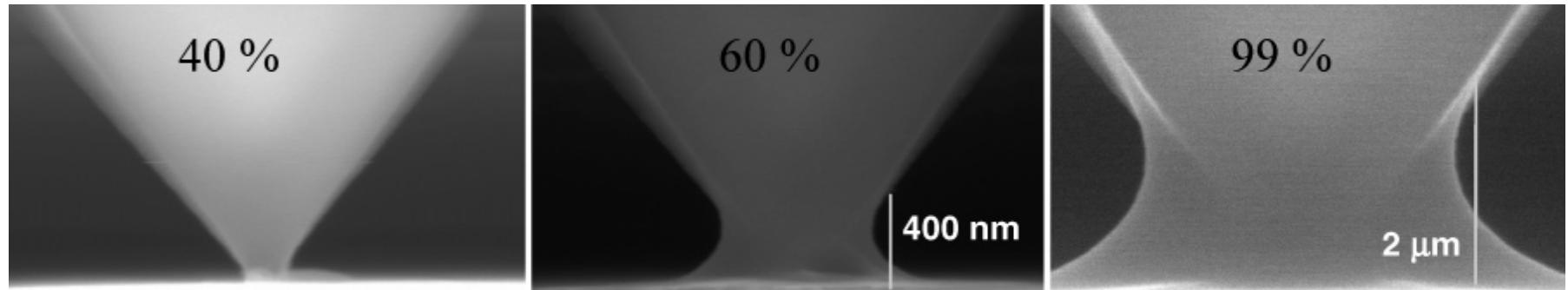


Surprisingly, single charge provides good description

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UT-BATTELLE

# Why is Tip so Large?

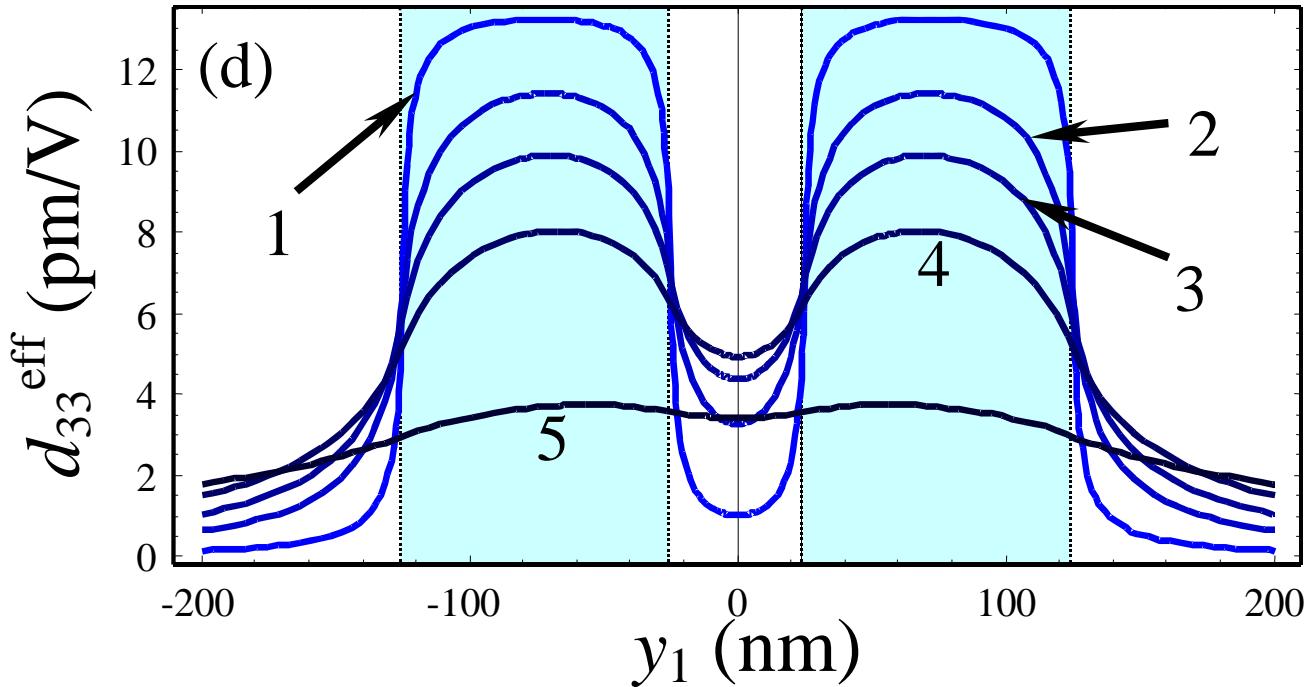


Langmuir **21**, 8096-8098 (2005)

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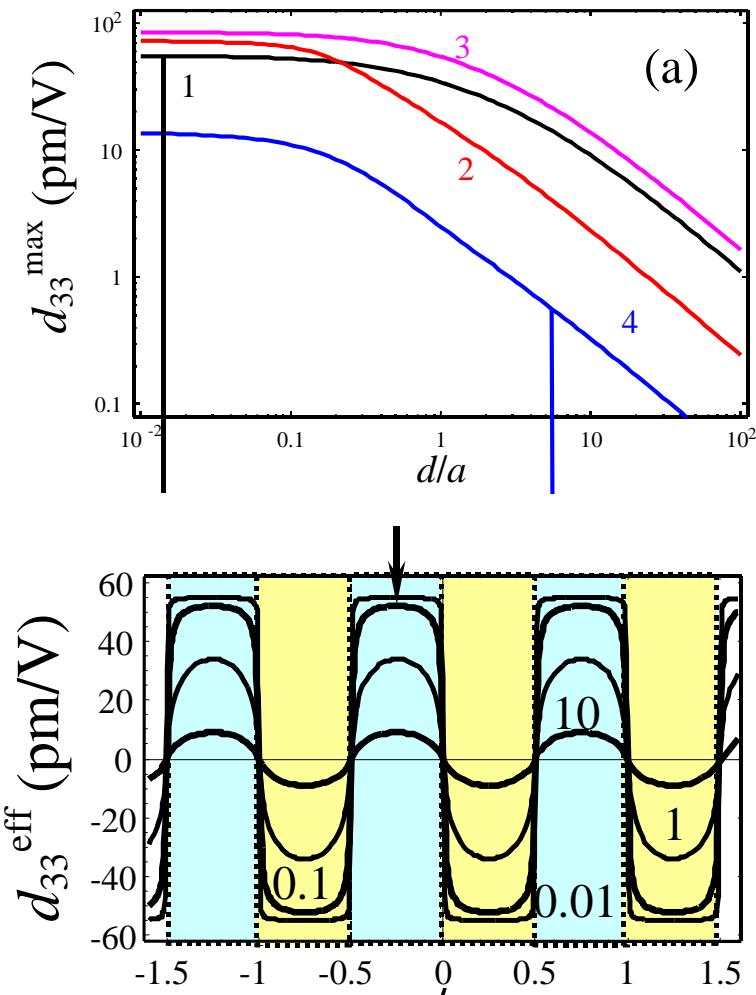


# *Effect of finite resolution on imaging*



- For low resolutions, domains are difficult to distinguish
- Signal in the center of domain decreases
- However, the domains are always visible

# Periodic Domain Structures



**Ideal Image**

$$d_{klj}(y) = d_{klj} \sum_{n=0}^{\infty} \frac{4}{(2n+1)\pi} \sin\left(\frac{2\pi}{a}(2n+1)y_1\right)$$

**Real Image**

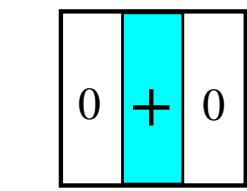
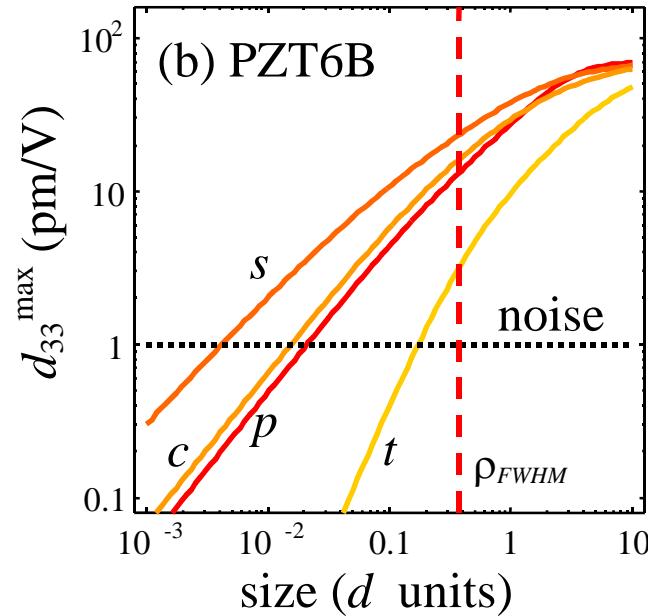
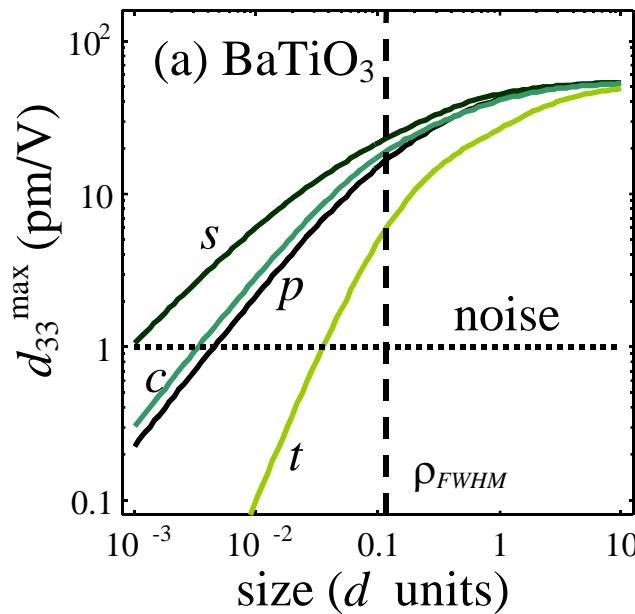
$$u_3(a, y_1) = \sum_{n=0}^{\infty} \frac{4}{(2n+1)\pi} \sin\left(\frac{2\pi}{a}(2n+1)y_1\right) F_q\left(\frac{2\pi}{a}(2n+1)\right)$$

**For low resolution, only one component survives:**

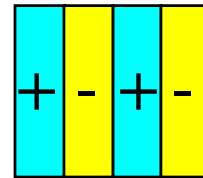
$$u_3(y) = \frac{4}{\pi} \sin\left(\frac{2\pi y_1}{a}\right) F_q\left(\frac{2\pi}{a}\right)$$

# Information Limit

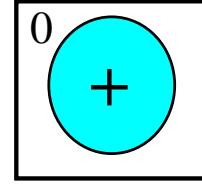
The smallest visible feature size is determined by the noise level of the system



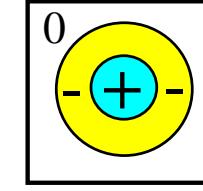
single stripe ( $s$ )  
size =  $a/d$



periodic stripes ( $p$ )  
size =  $a/d$



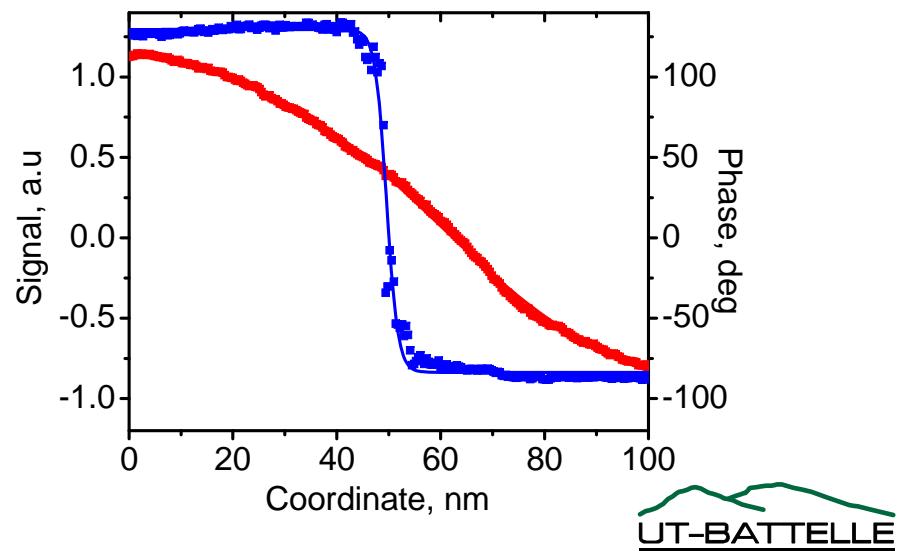
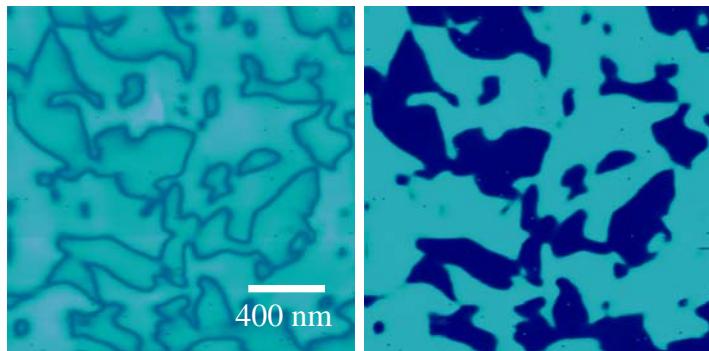
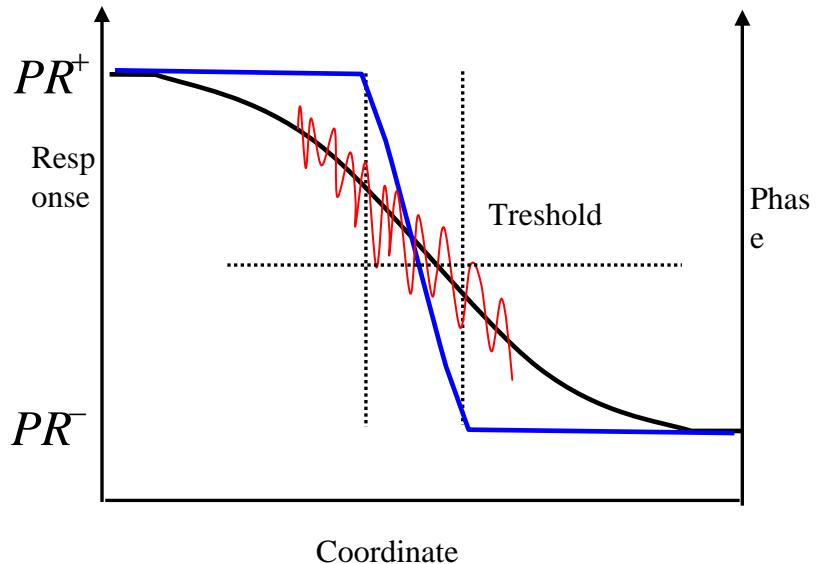
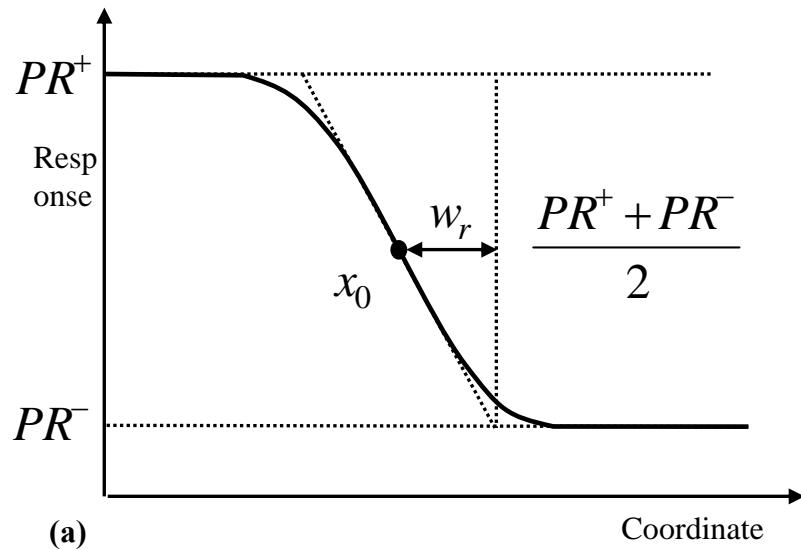
cylinder ( $c$ )  
size =  $r/d$



nested cylinders ( $t$ )  
size =  $r_o/d$

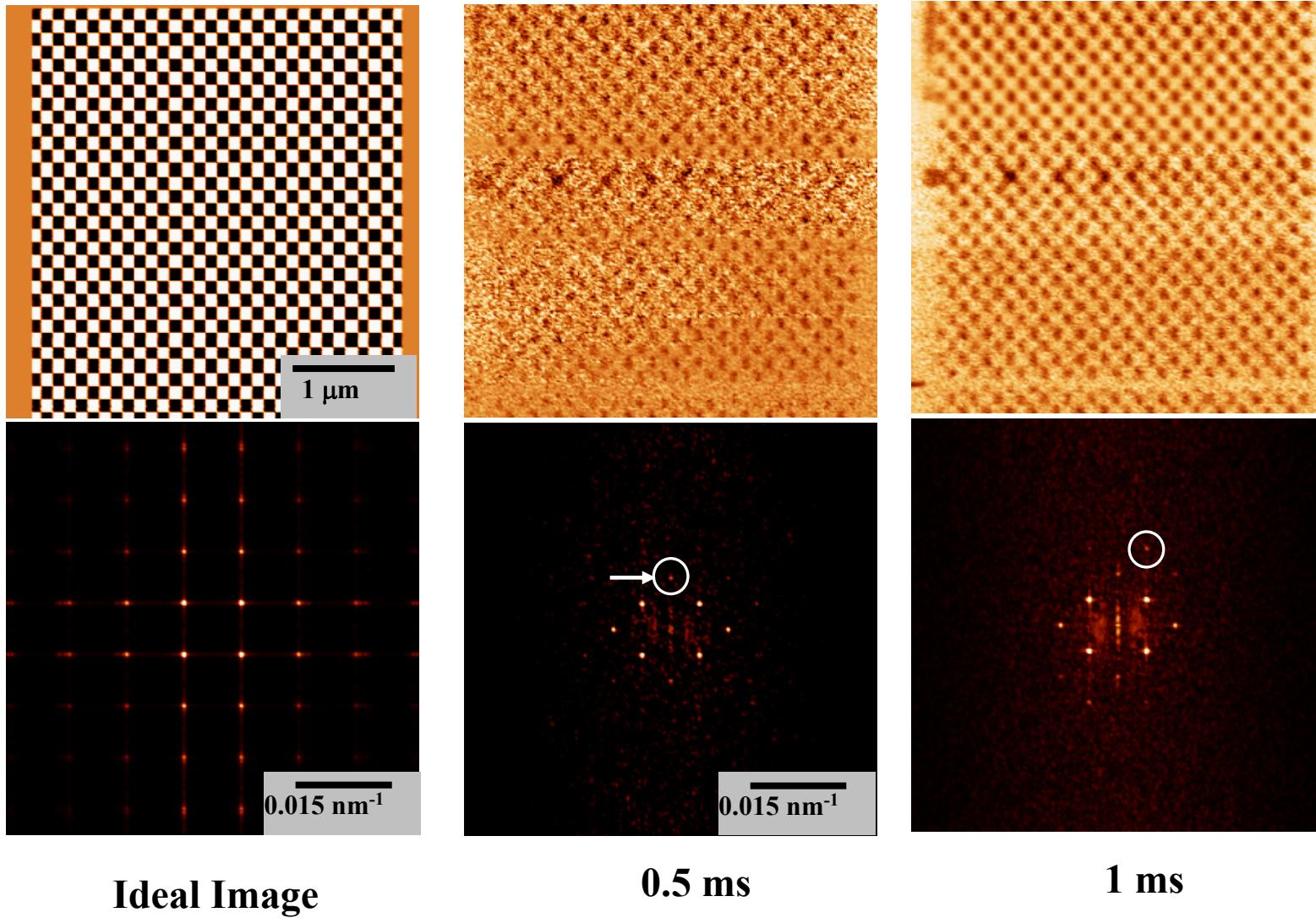
# Information Limit

Raleigh resolution in phase image is equal to information limit in mixed signal image



# *Lock-In Effect on Imaging*

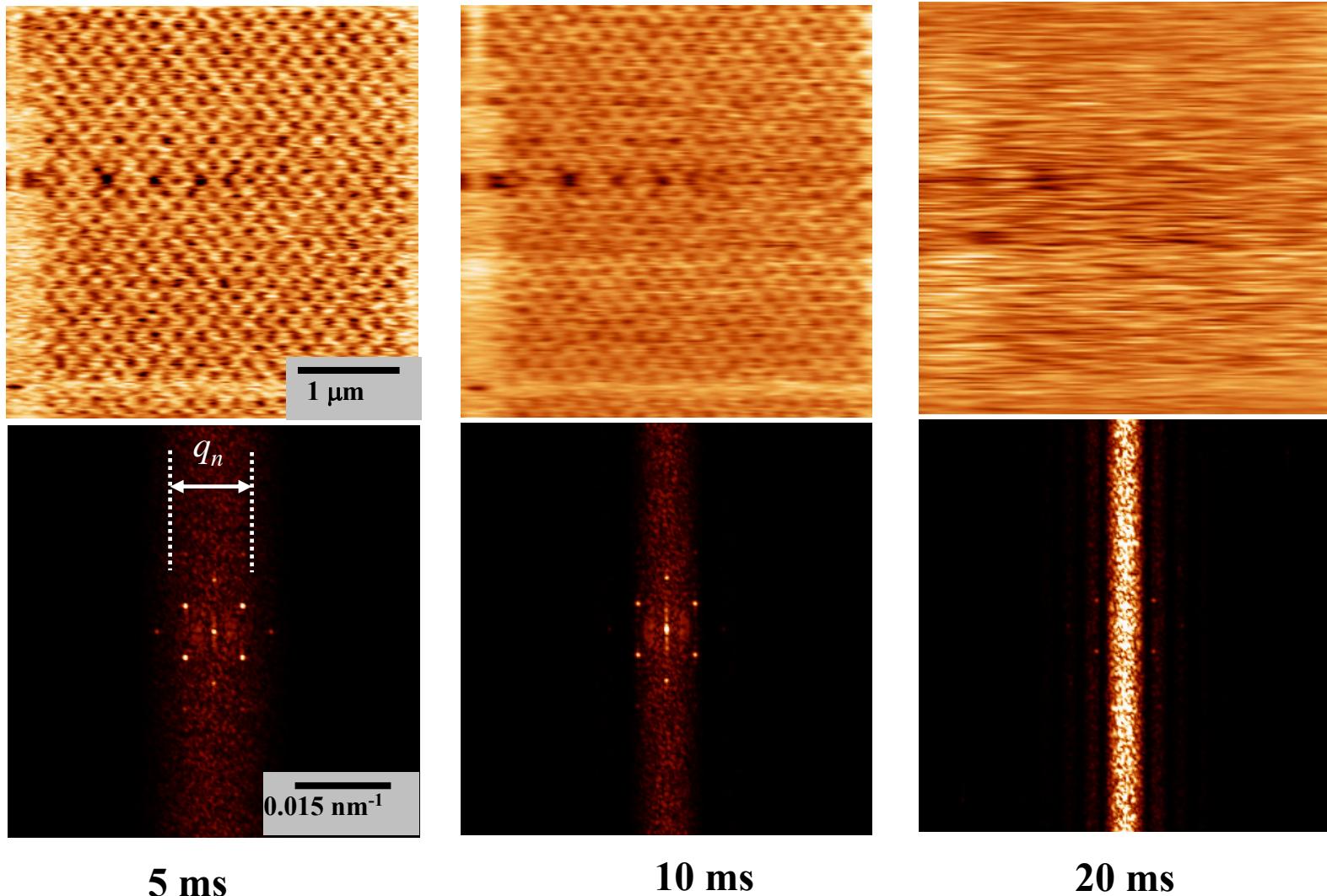
Time in each point  $\sim 4$  ms



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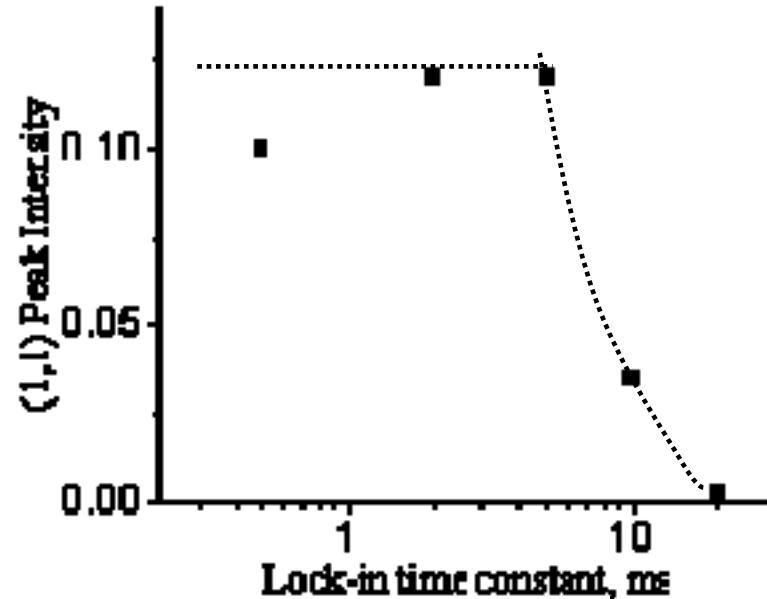
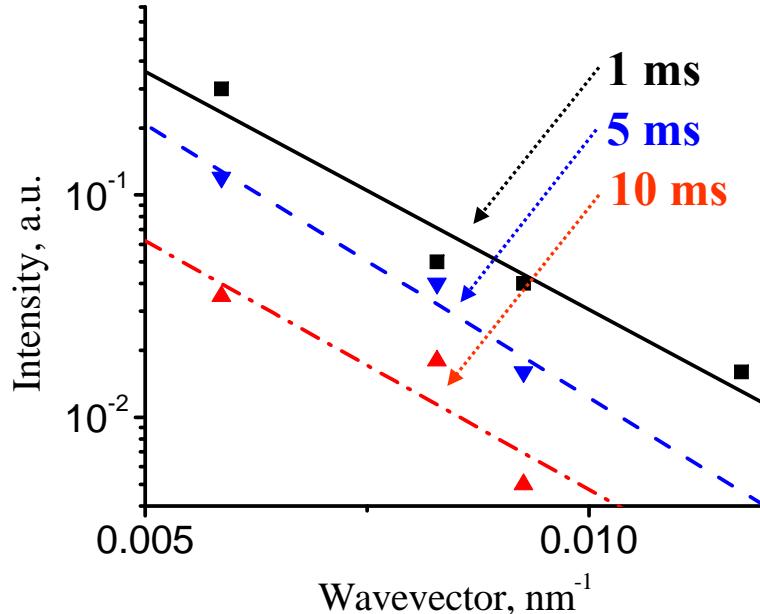
# *Lock-In Effect on Imaging*



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# Lock-In Effect on Imaging



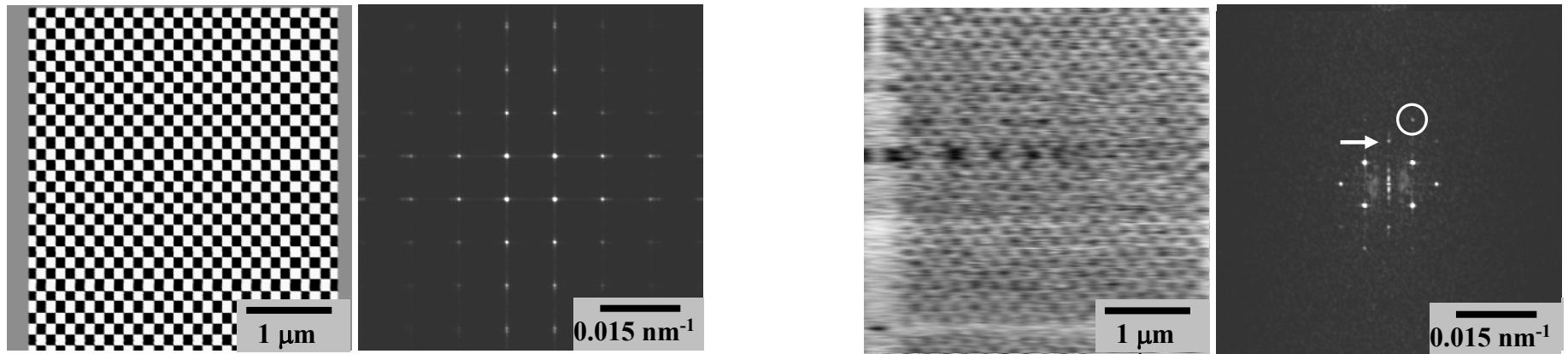
The wavevector dependence of peak intensity:  $I(hk) = I_0 \exp(-q/G)$

Resolution function is a product of lock-in and tip parts:  $F(\mathbf{q}) = F_{tip}(q)F_{la}(q_x)$

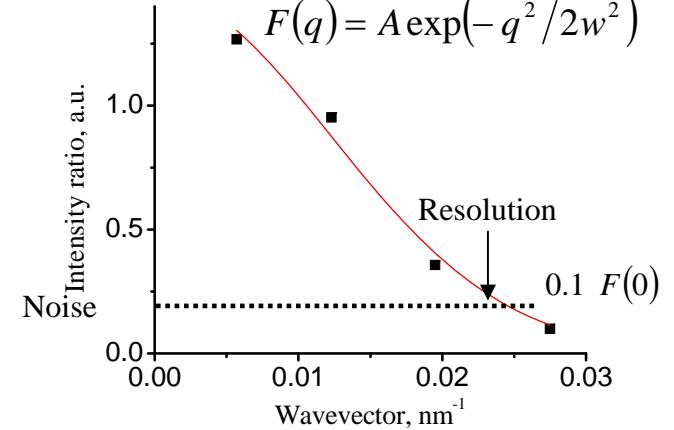
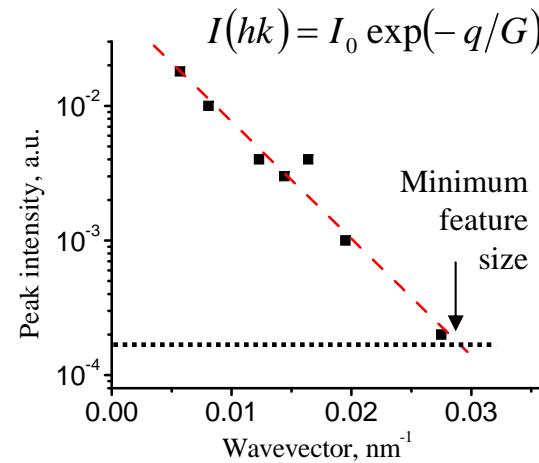
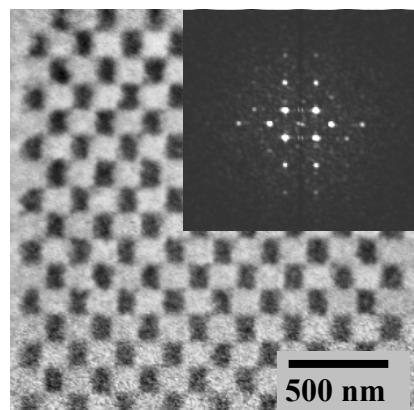
For small time constants  $\tau \ll \tau_{pixel}$  we have  $F_{la}(q_x) = 1$  but  $N(q) \sim \sqrt{\tau_{pixel}/\tau}$

For large time constants noise is small, but image is streaky

# *Application of Linear Imaging Theory to PFM*



*Checkerboard standard*



# Transfer Function and Image Reconstruction

Variable mesh size standard

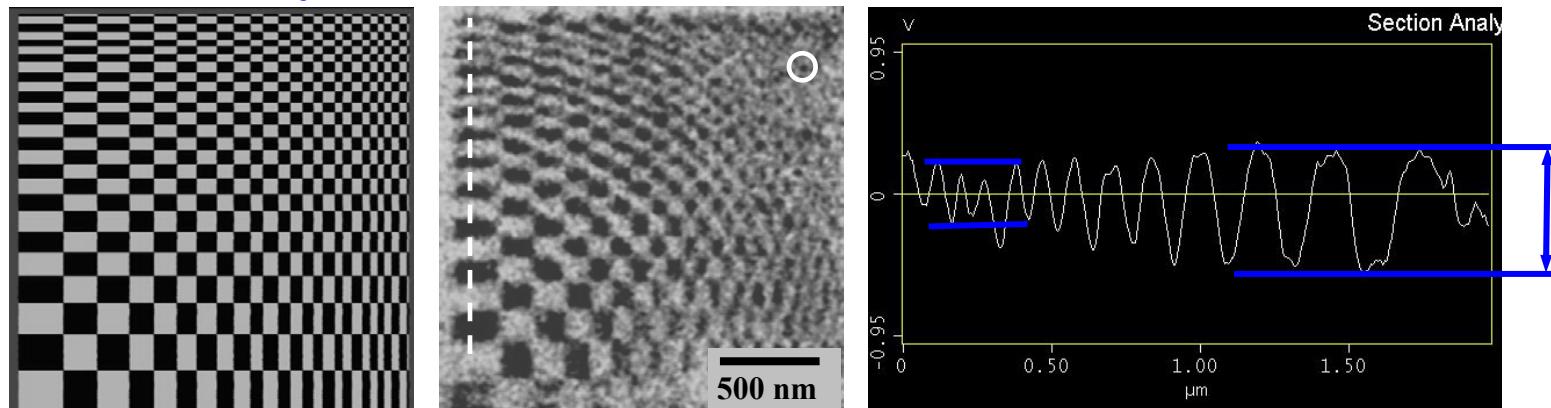
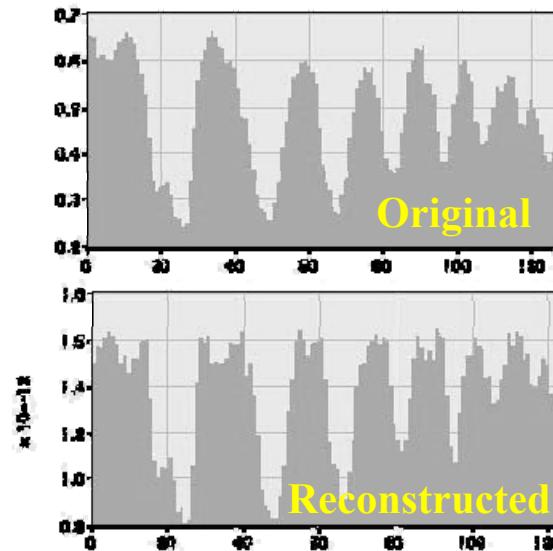
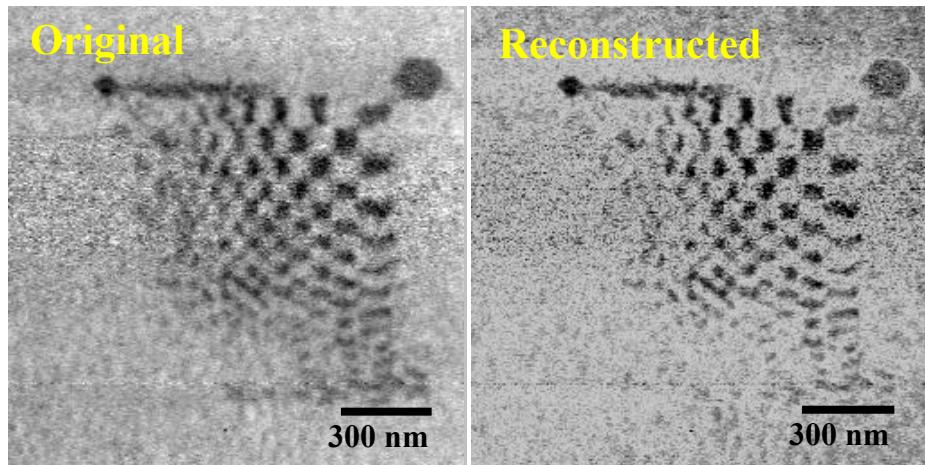
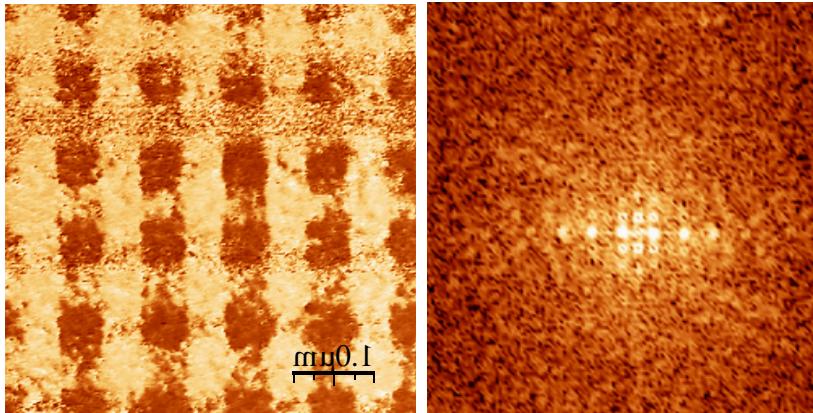


Image reconstruction using transfer function



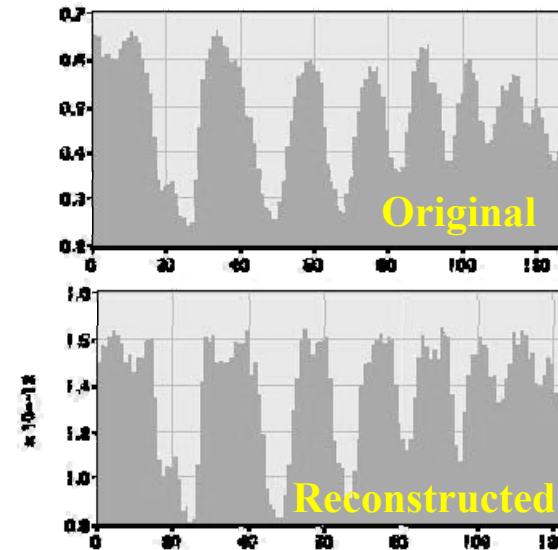
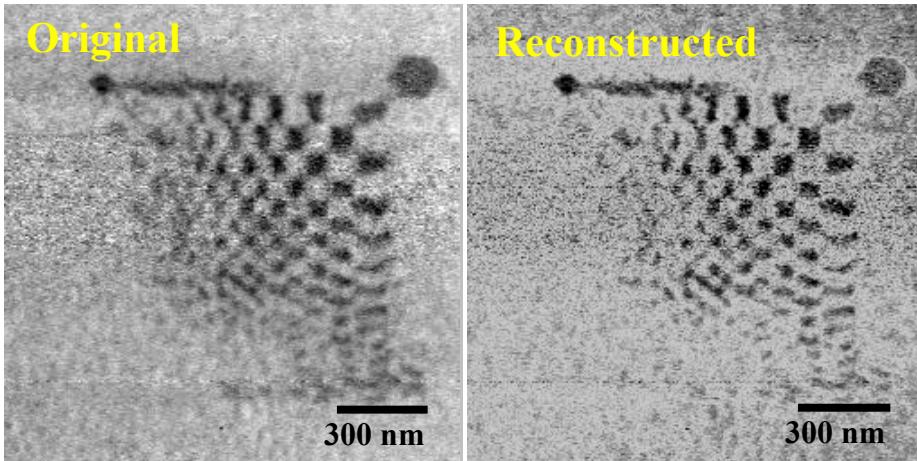
- Variable mesh size standard allow determination of minimal writable/detectable domain size
- Checkerboard standard allows resolution to be determined
- For epitaxial PZT film, minimum domain size is determined by resolution, rather then writing process
- Using known transfer function, PFM image can be reconstructed from experimental data.

# *Transfer Function and Image Reconstruction*



For sol-gel and inhomogeneous films, minimum domain size can be much larger than resolution as controlled by microstructure

## *Image reconstruction using transfer function*



Using known transfer function, PFM image can be reconstructed from experimental data.